

On a fixed point theorems for multivalued maps in b-metric space

AMAL M. HASHM

DUAA L.BAQAIR

Department of Mathematics, College of Science, University of Basrah,Iraq

amalmhashim@yahoo.com

Abstract:

In this paper, we prove the existence of the fixed points for circic's contractive condition combing with Berinde condition the class of so called circic strong almost contraction in b-metric spaces. The circic strong almost contraction appear to be one of the most general metrical condition for which the set of fixed points is not a singleton.

Our results extend and unify a multitude of fixed point theorems for multivalued maps.

Mathematics Subject Classifications (2000): 54H25, 47H10.

Keywords: fixed point, b-metric space, multivalued map

1-Introduction:

The concept of b-metric space was introduced by Czerwik((1998), since then several papers deal with fixed point theory for singlevalued and multivalued operators in b-metric see Singh et al.(2005),Boriceanu (2009) and Hashim (2011) . Our purpose is to show that some well-known fixed point theorems are valid in b-metric spaces.

Let (X, d) be a metric space and $CL(X)$ denotes the class of all nonempty

closed subset of X and $CB(X)$ denotes the class of all nonempty closed bounded subset of X . For A, B, C we consider $d(x, B) = \inf \{d(x, y); y \in B\}$, the distance between x and B . For any $A, B \in CL(X)$, define a function $H : CL(X) \times CL(X) \rightarrow [0, \infty]$

$$H(A, B) = \max \{ \sup_{x \in A} d(x, B), \sup_{y \in B} d(y, A) \},$$

then, H is said to be the generalize Housdorffmetric on $CL(X)$ induced by the metric d , see for instance Czerwik S.

Theorem (1.1):Czerwik(1998)

Let (X, d) be a complete b-metric space. If $T : X \rightarrow CL(X)$, satisfies the inequality $H(Tx, Ty) \leq \alpha d(x, y)$, $x, y \in X$, where $0 \leq \alpha \leq b^{-1}$, Then

- (i) for every $x_0 \in X$, there exist a sequence $\{x_n\} \subset X$ and $u \in X$ such that $x_{n+1} \in Tx_n$, $n = 0, 1, 2, 3, \dots$, and $\lim_{n \rightarrow \infty} x_n = u$,
- (ii) the point u is a fixed point of T , i.e $u \in Tu$.

Theorem (1.2): Berinde et al.(2007)

Let (X, d) be a complete metric space, $T : X \rightarrow CB(X)$ be a multivalued map and $L \geq 0$. Assume that $H(Tx, Ty) \leq \alpha(d(x, y))d(x, y) + Ld(y, Tx)$, for all $x, y \in X$, where α is a function from $[0, \infty)$ into $[0, \infty)$ satisfying

$\lim_{s \rightarrow t^+} \sup \alpha(s) < 1$ for all $t \in [0, \infty)$. Then $F(T) \neq \emptyset$ where $F(T)$, the set of fixed point of T . As known, a mapping $\varphi : R_+ \rightarrow R_+$ is called a comparison function if it is increasing and $\varphi^n(t) \rightarrow 0, n \rightarrow \infty$, for any $t \in R_+$

Lemma (1.3):Rus(2001)

If $\varphi: R^+ \rightarrow R^+$ is a comparison function, then;

1) each iterate φ^k of φ , $k \geq 1$, is also a comparison function:

- 2) φ is continuous at zero;
- 3) $\varphi(t) < t$, for any $t > 0$.

Let $T : X \rightarrow CL(X)$ and consider the following condition for all $x, y \in X$:

1) $H(Tx, Ty) \leq \alpha(d(x, y)) + Ld(y, Tx)$, where $L \geq 0$ and $0 < \alpha < 1$

2) $H(Tx, Ty) \leq \alpha M(x, y)$,

where $M(x, y) = \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2}[d(x, Ty) + d(y, Tx)] \right\}$,

3) $H(Tx, Ty) \leq \alpha M(x, y) + Ld(y, Tx)$,

4) $H(Tx, Ty) \leq \varphi M_1(x, y) + Ld(y, Tx)$.

Where $M_1(x, y) = \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2b}[d(x, Ty) + d(y, Tx)] \right\}$, where φ is

b-comparison function with $\varphi(z) = \frac{z}{b}$, $\varphi(0) = 0$, $b \geq 1$.

Remark (1.4):

Condition (1) is a very general contractive condition that allows the operator T to have more than one unique fixed point and it includes many contractive conditions from Rhoades' classification Rhoades(1977) and it is called a multivalued weak (almost)

contraction, see Berinde et al.(2007). Condition (1) and (2) are independent.

Condition (3) introduced by Berinde(2009) and by replacing the term $\alpha d(x, y)$ in (1) by $\varphi M_1(x, y)$ we get contractive condition (1). It is obvious that condition (4) is more general

contractive condition than (1) ,(2) and (3).

2. Preliminaries

Consistent with Hashim(2011) and Czerwik(1998) we use the following notations and definitions.

- 1) $d(x, y) = 0$ iff $x = y$,
- 2) $d(x, y) = d(y, x)$,
- 3) $d(x, z) \leq b[d(x, y) + d(y, z)]$.

The pair (X, d) is called a b-metric space. We remark that a metric space is evidently a b-metric space. However, Czerwik [1] has shown a b-metric on X need not be a metric space on X.

Example (2.2):Czerwik(1998).

Let $X = \{x_1, x_2, x_3\}$ and $d : X \times X \rightarrow R^+$ such that $d(x_1, x_3) = a \geq 2$, $d(x_1, x_3) = d(x_2, x_3) = 1$ and $d(x_n, x_n) = 0$, $d(x_n, x_k) = d(x_k, x_n)$ for $n, k = 1, 2, 3, \dots$. Then, $d(x_n, x_k) \leq \frac{a}{2}[d(x_n, x_i) + d(x_i, x_k)]$, $n, k, i = 1, 2, 3$. Then (X, d) is a b-metric space. And if $a > 2$, the ordinary triangle inequality does not hold.

Definition (2.3):Boriceanu (2009)

Let (X, d) be a b-metric space. Then a sequence $\{x_n\}_{n \in N}$ in X is called

Definition (2.1): Czerwik(1998).

Let X be a nonempty set and $b \geq 1$ a given real number. A function $d : X \times X \rightarrow R^+$ (nonnegative real numbers) is called a b-metric space provided that, for all $x, y, z \in X$,

The following example show b-metric on X not be a metric on X .

- a) Cauchy if and only if for every $\varepsilon > 0$ there exists $n(\varepsilon) \in \mathbb{N}$ such that for each $n, m \geq n(\varepsilon)$ we have $d(x_n, x_m) < \varepsilon$.
- b) Convergent if and only if there exists $x \in X$ such that for all $\varepsilon > 0$ there exists $n(\varepsilon) \in \mathbb{N}$ such that for all $n \geq n(\varepsilon)$ we have $d(x_n, x) < \varepsilon$.
- c) The b-metric space is complete if every Cauchy sequence converges.

Lemma (2.4): Czerwik(1998).

For any $A, B, C \in CL(X)$.

- (i) $d(x, B) \leq d(x, y)$, for any $y \in B$.
- (ii) $d(A, B) \leq H(A, B)$,
- (iii) $d(x, B) \leq H(A, B)$, $x \in A$
- (iii) $H(A, C) \leq s [H(A, B) + H(B, C)]$,
- (iv) $d(x, A) \leq sd(x, y) + sd(y, A)$, $x, y \in X$.

Lemma (2.5): Czerwik(1998):

Let (X, d) be a b-metric space and $A, B \in CL(X)$. Then for each $\alpha > 0$ and for all $b \in B$ there exists $a \in A$ such that $d(a, b) \leq H(A, B) + \alpha$.

Lemma (2.6): Singh et al. (2008).

Let (X, d) be a b-metric space and $\{y_n\}$ is a sequence in X such that $d(y_{n+1}, y_{n+2}) \leq qd(y_n, y_{n+1})$, $n = 0, 1, 2, \dots$

Then the sequence in X $\{y_n\}$ is a Cauchy sequence in X , provided that $sq < 1$ where $q \in (0, 1)$ and $s \geq 1$

Lemma 2.7: Pacurar(2010)

Any b-comparison function is a comparison function.

3. Main Results

Theorem (3.1):

Let (X, d) be a complete b-metric space with constant $b \geq 1$ and $T : X \rightarrow CL(X)$ a multivalued operator. Suppose that there exists a continuous $\varphi : R^+ \rightarrow R^+$ with $\varphi(z) = \frac{z}{b}$, $\varphi(0) = 0$, and for all $x, y \in X$. We have $H(Tx, Ty) \leq \varphi M_1(x, y) + Ld(y, Tx)$, with strict inequality if $M_1(x, y) \neq 0$. Where

$M_1(x, y) = \text{Max} \left\{ d(x, y), d(x, Tx), d(y, Ty), \frac{1}{2b} [d(x, Ty) + d(y, Tx)] \right\}$. Then T has a fixed point.

Proof:

Let $x_0 \in X$ and $x_1 \in Tx_0$. If $H(Tx_0, Tx_1) = 0$. Then, $Tx_0 = Tx_1$; that is $x_1 \in T_1$, which implies that $\text{Fix}(T) \neq \emptyset$.

Let $H(Tx_0, Tx_1) \neq 0$. Since $H(Tx_0, Tx_1) < \varphi(M_1(x_0, x_1)) + Ld(x_1, Tx_1)$, by Lemma (2.5) we may choose $\epsilon > 0$ with

$$H(Tx_0, Tx_1) + \epsilon \leq \varphi(M_1(x_0, x_1)) + Ld(x_1, Tx_0) \leq \varphi(M_1(x_0, x_1)),$$

Next we choose $x_2 \in Tx_1$ such that

$$d(x_1, x_2) \leq H(Tx_0, Tx_1) + \epsilon \leq \varphi(M_1(x_0, x_1)) \leq \varphi \max \{ d(x_0, x_1), d(x_0, Tx_0), d(x_1, Tx_1), \frac{1}{2b} [d(x_0, Tx_1) + d(x_1, Tx_0)] \}$$

There is 4 cases,

1) If $M_1(x_0, x_1) = d(x_0, x_1)$. Then ,

$$d(x_1, x_2) \leq \varphi d(x_0, x_1), \tag{3.1}$$

2) If $M_1(x_1, x_0) = d(x_0, Tx_0)$, then we have,

$$d(x_1, x_2) \leq H(Tx_0, Tx_1) + \varphi M(x_0, x_1) + Ld(x_1, Tx_0) \leq \varphi d(x_0, x_1) < d(x_0, x_1),$$

3) If $M_1(x_0, x_1) = d(x_1, Tx_1)$, then,

$$d(x_1, x_2) \leq \varphi d(x_1, Tx_1) + Ld(x_1, Tx_0) \leq \varphi d(x_1, Tx_1) < d(x_1, x_2),$$

4) If $M_1(x_0, x_1) = \frac{1}{2b} [d(x_0, Tx_1) + d(x_1, Tx_0)] = \frac{1}{2b} d(x_0, Tx_1)$, then,

$$d(x_1, x_2) \leq \varphi \left[\frac{1}{2b} d(x_0, Tx_1) \right] < \frac{1}{2b} d(x_0, Tx_1) \leq \frac{1}{2b} d(x_0, x_2) \leq \frac{1}{2} [d(x_0, x_1) + d(x_1, x_2)],$$

Hence $d(x_1, x_2) < \frac{1}{2} d(x_0, x_1)$.

Thus (3.1) is true in all cases, $d(x_1, x_2) \leq \varphi d(x_0, x_1) < d(x_0, x_1)$. Next we assume

$M_1(x_1, x_2) \neq 0$ choose $\delta > 0$ with $H(Tx_1, Tx_2) + \delta \leq \varphi(M_1(x_1, x_2) + Ld(x_2, Tx_1))$

Let $x_3 \in Tx_2$ such that, $d(x_2, x_3) \leq H(Tx_1, Tx_2) + \delta \leq \varphi(M_1(x_1, x_2))$.

If $M_1(x_2, x_3) = 0$, then $Fix(T) \neq \emptyset$

If $M_1(x_2, x_3) > 0$. Then, we will show that

$$d(x_2, x_3) \leq \varphi(d(x_1, x_2)) \leq \varphi^2 d(x_0, x_1), \quad (3.2)$$

Now if $M_1(x_1, x_2) = d(x_1, x_2)$, then (3.2) is true.

If $M_1(x_1, x_2) = d(x_1, Tx_1)$, then we have

$$d(x_2, x_3) \leq \varphi d(x_1, Tx_1) + Ld(x_3, Tx_2) \leq \varphi d(x_1, x_2), \text{ thus (3.2) is true.}$$

If $M_1(x_1, x_2) = d(x_2, Tx_2)$, then

$$d(x_2, x_3) \leq \varphi(d(x_2, Tx_2)) < d(x_2, Tx_2) \leq d(x_2, x_3), \text{ which is a contraction.}$$

If $M_1(x_1, x_2) = \frac{1}{2b}d(x_1, Tx_2)$, then, we have

$$d(x_2, x_3) \leq \varphi \left(\frac{1}{2b}d(x_1, Tx_2) \right) < \frac{1}{2}d(x_1, Tx_2) \leq \frac{1}{2b}d(x_1, x_3) \leq \frac{1}{2} [d(x_1, x_2) + d(x_2, x_3)],$$

Thus $d(x_2, x_3) < d(x_1, x_2)$, which is a contraction. Thus (3.2) is true.

Hence in all cases (3.2) is true.

By an inductively procedure we will obtain $x_{n+1} \in Tx_n$, for $n = 3, 4, \dots$ with

$$d(x_{n+1}, x_n) \leq \varphi M_1(x_{n-1}, x_n),$$

The argument above guarantees that

$$d(x_n, x_{n+1}) \leq \varphi(d(x_{n-1}, x_n) \leq \dots \leq \varphi^n(d(x_0, x_1)).$$

Next we will prove that $\{x_n\}$ is a Cauchy sequence

$$d(x_n, x_{n+p}) \leq bd(x_n, x_{n+1}) + b^2d(x_{n+1}, x_{n+2}) + \dots + b^pd(x_{n+p-1}, x_{n+p}),$$

$$d(x_n, x_{n+p}) \leq b\varphi^n d(x_0, x_1) + b^2\varphi^{n+1}d(x_0, x_1) + \dots + b^p\varphi^{n+p-1}d(x_0, x_1),$$

Which can also be written as

$$d(x_n, x_{n+p}) \leq \frac{1}{b^{n-1}} [b^n\varphi^n d(x_0, x_1) + b^{n+1}\varphi^{n+1}d(x_0, x_1) + b^{n+p-1}\varphi^{n+p-1}d(x_0, x_1)]$$

$$\leq \frac{1}{b^{n-1}} \sum_{j=n}^{\infty} b^j \varphi^j d(x_0, x_1) \rightarrow 0, \text{ as } n \rightarrow \infty.$$

Thus $\{x_n\}$ is Cauchy sequence in the complete b-metric space (X, d) . So there is $x^* \in X$ such that $x^* = \lim_{n \rightarrow \infty} x_n$.

In the following we prove that x^* is a fixed point of T i.e. $x^* \in Tx^*$.

$$d(x^*,Tx^*) \leq b[d(x^*,x_n) + d(x_n,Tx^*)] \leq b[d(x^*,x_n) + H(Tx_{n-1},Tx^*)] \leq b[d(x^*,x_n) + \varphi(M_1(x_{n-1},x^*))] + Ld(x^*,Tx_{n-1}) = bd(x^*,x_n) + b(\varphi M_1(x^*,x_{n-1})).$$

For

$$n \rightarrow \infty,$$

$$d(x^*,Tx^*) \leq b\varphi(\max\{0,0,d(x^*,Tx^*)\}, \frac{1}{2b}(d(x^*,Tx^*))) \leq b\varphi d(x^*,Tx^*) < d(x^*,Tx^*),$$

Which implies that $d(x^*,Tx^*) = 0$, so that $x \in \overline{Tx} = Tx, (\overline{T}$ is the closure of T).

Remark (3.2):

(1) If $L = 0$ in condition then we obtain theorem (3.1) of Boriceanu(2009).

(2) If $\varphi(z) = \alpha z$ in condition (4) then we obtain corollary(3.1) of Singh et al.(2008) with $Y = X$ and $f = I$.

(3) Theorem (3.1) generalize the main results of Pacurar (2010), Pacurar (2013) and Singh *et al.*(2012).

References

Berinde M. and Berinde V., (2007) On general class of multivalued weakly Picard mapping, J. Math. Anal, 326, 772-782.

Berinde, V., (2009) Some remarks on a fixed point theorem for Ciric-type almost

contraction, Carpathian J-Math 25, No.2, 157-162.

Boriceanu M., (2009) Strict fixed point theorem for multivalued operators in b-metric spaces International Journal of Modern Mathematics 4(2), 1-17.

Czerwik S., (1998) Nonlinear set valued contraction in b-metric spaces. Attisem . Mat.Univ. Modena, 46, 263-276.

Hashim A.M., (2011) Stability of iterative procedures for hybrid maps in b-metric space. Basrah Journal of science(A) 29(1), 74-84.

Kir.M, Kiziltunc.H, (2013): On some well-known fixed point theorems in b-metric space, Turkish Journal of analysis and number theory 1.1 ,13-26.

Pacurar, M., (2010) A fixed point result for φ -contraction on b-metric spaces without the boundedness assumption, Fasciculi Mathematici ,No.43, 127-137.

Rhoades, B.E., (1977) A comparison of various definitions of contractive mappings, Trans, Amer, Math.Soc.226,257-290.

Rus, I.A., (2001) Generalized Contractions and Applications, Cluj university press Cluj- Napoca.

Singh S.L., Bhatnagar C, Mishra S.N., (2005) Stability of iterative procedure for

multivalued maps in metric spaces, Demonstratio. Math, 37, 905-916.

Singh S.L., Czerwik S., Krol Krzysztof, and Singh Abba., (2008) Coincidences and fixed points of hybrid contractions, Tamsui Oxford Journal of Mathematical sciences,24(4), 401-416.

Singh, A and Alam, A., (2012) Zamfirescu maps and its stability on generalized space. International Journal of Engineering and Technology (IJEST) Vol. 4 No.01,331-335.

حول مبرهنات النقطة الصامدة للدوال المتعددة القيم في الفضاء المترى b

امل محمد هاشم البطاط

دعاء لفقة باقر

قسم الرياضيات- كلية العلوم -جامعة البصرة

الخلاصة

في هذا البحث برهن على وجود النقاط الصامدة باستخدام شرط Ciric وشرط Berinde معا في الفضاء المترى b . ان شرط Ciric المسمى بالانكماش القوي تقريبا هو من اكثر الشروط تعميما والذي تكون فيه النقاط الصامدة ليست وحيدة . في هذا البحث توحيد وتوسيع بعض مبرهنات النقطة الصامدة للدوال متعددة القيم.