



## تقدير دالة المعولية لبعض مكائن الشركة العامة لصناعة الأسمدة المنطقة الجنوبية

### باتباع سياسة الفحص والصيانة الوقائية

Estimating of Reliability function for the Equipment of the state Company for Fertilizer manufacturing, South region by using the policy of Replacement and miantence

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المستخلص

#### ABSTRACT

Recently, there have been considerable methods developed in the field of Reliability Engineering in order to help the management in determining the Reliability function of their equipments and combined this function with the miantence and Replacements methods.

The aim of this research is to develop methods in order to find the Reliability function based on the empirical distribution of the delay time by using an actual data from the Real life of a production company.



1. المقدمة Introduction

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Operating Time

Inspection Policy

Delay Time

2. الموثوقية Reliability

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Exponential Distribution -

Weibull Distribution -

Gamma Distribution -



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Lognormal Distribution -

Life Time Data

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٣. الصياغة الرياضية لدالة المعولية تحت سياسة الفحص

t

: ( ) R(t)

$$R(t) = 1 - F(t)$$

m t<sub>c</sub> t

: ( )

$$R_{t_c}^{(m)}(t)$$

$$R_{t_c}^{(m)}(t) = \left\{ \sum_{j=1}^{m-1} \left[ \left( \int_{(j-1)t_c}^{jt_c} g(t_o) z(jt_c - t_o) dt_o \right) R_{t_c}^{(m-j)}(t - jt_c) \right] + \int_t^{\infty} g(t_o) dt_o \right. \\ \left. + \int_{(m-1)t_c}^t g(t_o) z(t - t_o) dt_o \right\} \dots(1)$$

:

$$(m-1)t_c \leq t < mt_c$$

.t<sub>o</sub>

: g(t<sub>o</sub>)

t

: z(t)

-: ( )

$$z(t) = \int_t^{\infty} f(t_d) dt_d = 1 - F(t) \dots(2)$$





$$R_{t_c}^{(m)}(t) \quad t_d \quad f(t_d)$$

$$-:$$

$$: (\cdot)$$

$$g(t_0) \quad t_d \quad t_0$$

$$g(t_0) = \begin{cases} \alpha \beta^{-\alpha} t_0^{(\alpha-1)} e^{-(t_0/\beta)^\alpha} & ; t_0 \geq 0, \alpha, \beta > 0 \\ 0 & ; otherwise \end{cases} \quad \dots(3)$$

$$\alpha = 1$$

$$g(t_0) = \begin{cases} (1/\beta) e^{-(t_0/\beta)} & ; t_0 \geq 0, \beta > 0 \\ 0 & ; otherwise \end{cases} \quad \dots(4)$$

$$f(t_d) = \begin{cases} \gamma \theta^{-\gamma} t_d^{(\gamma-1)} e^{-(t_d/\theta)^\gamma} & ; t_d \geq 0, \gamma, \theta > 0 \\ 0 & ; otherwise \end{cases} \quad \dots(5)$$

$$f(t_d) = \begin{cases} (1/\theta) e^{-(t_d/\theta)} & ; t_d \geq 0, \theta > 0 \\ 0 & ; otherwise \end{cases} \quad \dots(6)$$

$$: \quad f(t_d) \quad t_d \quad \gamma = 1$$



- ) ( ) ..... .. .. (



: ( )  $R_{t_c}^{(m)}(t)$  : ( ) ( )

$$\int_t^\infty g(t_o) dt_o = e^{-(t/\beta)^\alpha} \quad \dots(7)$$

$$z(t) = \int_t^\infty f(t_d) dt_d = e^{-(t/\theta)^\gamma} \quad \dots(8)$$

$$\int_{(j-1)t_c}^{jt_c} g(t_o) z(jt_c - t_o) dt_o = \frac{\alpha}{\beta} \int_{(j-1)t_c}^{jt_c} (t_o / \beta)^{(\alpha-1)} e^{\frac{(t_o \theta^\gamma + (jt_c - t_o)^\gamma \beta^\alpha)}{\beta^\alpha \theta^\gamma}} dt_o \quad \dots(9)$$

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:

$$\int_{(j-1)t_c}^{jt_c} g(t_o) z(jt_c - t_o) dt_o \cong \frac{h\alpha}{3\beta} \left[ \left( (j-1)t_c / \beta \right)^{(\alpha-1)} e^{\frac{-((j-1)t_c)^\alpha \theta^\gamma + t_c^\gamma \beta^\alpha}{\beta^\alpha \theta^\gamma}} + \right.$$

$$\left. 4 \sum_{i=1}^{n/2} k[(j-1)t_c + (2i-1)h] + 2 \sum_{i=1}^{n/2-1} k[(j-1)t_c + 2ih] + (jt_c / \beta)^{(\alpha-1)} e^{-(jt_c / \beta)^\alpha} \right] \quad \dots(10)$$

$((j-1)t_c, jt_c)$

$n \quad h = t_c / n$

$$k(t_o) = (t_o / \beta)^{(\alpha-1)} e^{\left( \frac{(t_o \theta^\gamma + (jt_c - t_o)^\gamma \beta^\alpha)}{\beta^\alpha \theta^\gamma} \right)} \quad \dots(11)$$

$$\int_{(m-1)t_c}^t g(t_o) z(t - t_o) dt_o = \frac{\alpha}{\beta} \int_{(m-1)t_c}^t (t_o / \beta)^{(\alpha-1)} e^{\frac{(t_o \theta^\gamma + (t - t_o)^\gamma \beta^\alpha)}{\beta^\alpha \theta^\gamma}} dt_o \quad \dots(12)$$



: ( )

$$\int_{(m-1)t_c}^t g(t_o) z(t - t_o) dt_o \cong \frac{h_1 \alpha}{3\beta} \left[ ((m-1)t_c / \beta)^{(\alpha-1)} e^{-\frac{((m-1)t_c)^\alpha \theta^\gamma + (t-(m-1)t_c)^\gamma \beta^\alpha}{\beta^\alpha \theta^\gamma}} \right. \\ \left. + 4 \sum_{i=1}^{n_1/2} k[(m-1)t_c + (2i-1)h_1] \right. \\ \left. + 2 \sum_{i=1}^{n_1/2-1} k[(m-1)t_c + 2ih_1 + (t/\beta)^{(\alpha-1)} e^{-(t/\beta)^\alpha}] \right] \dots(13)$$

$$k(t_o) = (t_o / \beta)^{(\alpha-1)} e^{-\frac{((t_o)^\alpha \theta^\gamma + (t-t_o)^\gamma \beta^\alpha)}{\beta^\alpha \theta^\gamma}} \quad h_{n_1} = (t - (m-1)t_c) / n_1 \dots(14)$$

( ) ( ) ( ) ( )

:

$$R_{t_c}^{(m)}(t) \cong \frac{h\alpha}{3\beta} \sum_{j=1}^{m-1} \left[ ((j-1)t_c / \beta)^{(\alpha-1)} e^{-\frac{((j-1)t_c)^\alpha \theta^\gamma + t_c^\gamma \beta^\alpha}{\beta^\alpha \theta^\gamma}} \right. \\ \left. + 4 \sum_{i=1}^{n/2} k[(j-1)t_c + (2i-1)h] + 2 \sum_{i=1}^{n_1/2-1} k[(j-1)t_c + 2ih] \right. \\ \left. + (jt_c / \beta)^{(\alpha-1)} e^{-(jt_c / \beta)^\alpha} \right] R_{t_c}^{(m-j)}(t - jt_c) + e^{-(t/\beta)^\alpha} \\ \left. + \frac{h_1 \alpha}{3\beta} \left[ ((m-1)t_c / \beta)^{(\alpha-1)} e^{-\frac{((m-1)t_c)^\alpha \theta^\gamma + (t-(m-1)t_c)^\gamma \beta^\alpha}{\beta^\alpha \theta^\gamma}} \right. \right. \\ \left. \left. + 4 \sum_{i=1}^{n_1/2} k[(m-1)t_c + (2i-1)h_1] + 2 \sum_{i=1}^{n_1/2-1} k[(m-1)t_c + 2ih_1] \right. \right. \\ \left. \left. + (t/\beta)^{(\alpha-1)} e^{-(t/\beta)^\alpha} \right] \dots(15)$$



- ) ( ) ..... .. (

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$$(m - 1)t_c \leq t < mt_c$$

$\gamma = 1$   $t_d$   $t_o$  ,  
 ( ) ( )  
 -:  $R_{t_c}^{(m)}(t)$

$$\begin{aligned}
 R_{t_c}^{(m)}(t) \cong & \frac{h\alpha^{m-1}}{3\beta} \sum_{j=1}^{n/2} \left[ \left( (j-1)t_c / \beta \right)^{(\alpha-1)} e^{-\frac{\left( (j-1)t_c \right)^\alpha \theta + t_c \beta^\alpha}{\beta^\alpha \theta}} \right. \\
 & + 4 \sum_{i=1}^{n/2} k[(j-1)t_c + (2i-1)h] + 2 \sum_{i=1}^{n/2-1} k[(j-1)t_c + 2ih] \\
 & \left. + (jt_c / \beta)^{(\alpha-1)} e^{-(jt_c / \beta)^\alpha} \right] R_{t_c}^{(m-j)}(t - jt_c) + e^{-(t / \beta)^\alpha} \\
 & + \frac{h_1 \alpha}{3\beta} \left[ \left( (m-1)t_c / \beta \right)^{(\alpha-1)} e^{-\frac{\left( (m-1)t_c \right)^\alpha \theta + (t - (m-1)t_c) \beta^\alpha}{\beta^\alpha \theta}} \right. \\
 & + 4 \sum_{i=1}^{m_1/2} k[(m-1)t_c + (2i-1)h_1] + 2 \sum_{i=1}^{m_1/2-1} k[(m-1)t_c + 2ih_1] \\
 & \left. + (t / \beta)^{(\alpha-1)} e^{-(t / \beta)^\alpha} \right] \dots (16)
 \end{aligned}$$





$$\alpha = 1 \quad \mathbf{t_d} \quad \mathbf{t_o} \quad ,$$

$$-: \quad R_{t_c}^{(m)}(t) \quad ( )$$

$$\begin{aligned}
 R_{t_c}^{(m)}(t) \cong & \frac{h}{3\beta} \sum_{j=1}^{m-1} \left[ e^{-\frac{-(j-1)t_c \theta^\gamma + t_c^\gamma \beta}{\beta \theta^\gamma}} \right. \\
 & + 4 \sum_{i=1}^{n/2} k[(j-1)t_c + (2i-1)h] + 2 \sum_{i=1}^{n/2-1} k[(j-1)t_c + 2ih] \\
 & \left. + e^{-(jt_c/\beta)} \right] R_{t_c}^{(m-j)}(t - jt_c) + e^{-(t/\beta)} \\
 & + \frac{h_1}{3\beta} \left[ e^{-\frac{-(m-1)t_c \theta^\gamma + (t-(m-1)t_c)^\gamma \beta}{\beta \theta^\gamma}} \right. \\
 & + 4 \sum_{i=1}^{n_1/2} k[(m-1)t_c + (2i-1)h_1] + 2 \sum_{i=1}^{n_1/2-1} k[(m-1)t_c + 2ih_1] \\
 & \left. + e^{-(t/\beta)} \right] \quad \dots(17)
 \end{aligned}$$

$$\mathbf{t_d} \quad \mathbf{t_o} \quad ,$$

$$\begin{aligned}
 & R_{t_c}^{(m)}(t) \\
 & : \quad ( ) \quad ( ) \quad ( )
 \end{aligned}$$

$$\int_{(j-1)t_c}^{jt_c} g(t_o) z(jt_c - t_o) dt_o = \frac{\theta}{\theta - \beta} \left[ e^{-\frac{((j-1)\theta + \beta)t_c}{\beta \theta}} - e^{-\frac{jt_c}{\beta}} \right] \quad \dots(18)$$

$$\int_{(m-1)t_c}^t g(t_o) z(t - t_o) dt_o = \frac{\theta}{\theta - \beta} \left[ e^{-\frac{(m-1)t_c \theta + (t-(m-1)t_c)\beta}{\beta \theta}} - e^{-\frac{t}{\beta}} \right] \quad \dots(19)$$

:

$$\begin{aligned}
 R_{t_c}^{(m)}(t) = & \left\{ \sum_{j=1}^{m-1} \left( \frac{\theta}{\theta - \beta} \left[ e^{-\frac{((j-1)\theta + \beta)t_c}{\beta \theta}} - e^{-\frac{jt_c}{\beta}} \right] r_{t_c}^{(m-j)}(t - jt_c) \right) + e^{-t/\beta} \right. \\
 & \left. + \frac{\theta}{\theta - \beta} \left[ e^{-\frac{(m-1)t_c \theta + (t-(m-1)t_c)\beta}{\beta \theta}} - e^{-\frac{t}{\beta}} \right] \right\} \quad \dots(20)
 \end{aligned}$$



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#### ٤. اختبارات تحديد التوزيع الاحتمالي

##### ( Test of Goodness of Fit) 4.1

Karl Pearson

:( )

$$\chi^2 = \sum_{i=1}^r \frac{(O_i - E_i)^2}{E_i} \quad \dots(21)$$

$E_i$  ( )  $O_i$  r

$$\chi^2 > \chi_{1-\alpha}^2(v)$$

$\alpha$   $v = r - m - 1$   $\chi^2$   $\chi_{1-\alpha}^2(v)$  m

##### : (K-S) 4.2

$\chi^2$  (K-S)

$$D = \sup_x |F_S(x) - F_T(x)| \quad \dots(22)$$

$F_S(x)$  (Distribution Function)  $F_T(x)$





l

$$K_{1-\alpha}(n) \quad D > K_{1-\alpha}(n)$$

. n                       $\alpha$

## ٥. التطبيق العملي

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Time Between Failure

( ) ( )

Dealy- Time

### جدول (١)

#### زمن الاشتغال لإحدى منظومات الترشيح

ت	زمن الاشتغال	ت	زمن الاشتغال	ت	زمن الاشتغال	ت	زمن الاشتغال
١	٨	١١	١٢	٢١	٨	٣١	١٤
٢	٧	١٢	١٤	٢٢	٨	٣٢	٨
٣	١٠	١٣	١٠	٢٣	٩	٣٣	٩
٤	٤	١٤	١٥	٢٤	٣	٣٤	٧
٥	٣	١٥	١٠	٢٥	٢	٣٥	٦
٦	٧	١٦	١٢	٢٦	١٤	٣٦	٢
٧	٧	١٧	٤	٢٧	١٤	٣٧	١
٨	٨	١٨	٦	٢٨	١٢		
٩	٨	١٩	٧	٢٩	١٣		
١٠	١٠	٢٠	٧	٣٠	١٢		

### جدول (٢)

#### أزمنة تأخير إصلاح العطلات لإحدى منظومات الترشيح

ت	زمن التأخير	ت	زمن التأخير	ت	زمن التأخير	ت	زمن التأخير
١	٥	١١	٢	٢١	٤	٣١	٣
٢	٤	١٢	٥	٢٢	٥	٣٢	٢
٣	٣	١٣	١	٢٣	٦	٣٣	٢
٤	٢	١٤	٢	٢٤	٤	٣٤	٤

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٣	٣٥	٢	٢٥	١	١٥	٤	٥
٥	٣٦	١	٢٦	٣	١٦	٥	٦
٦	٣٧	٣	٢٧	٢	١٧	٣	٧
٢	٣٨	٢	٢٨	١	١٨	٢	٨
		١	٢٩	٣	١٩	٤	٩
		٢	٣٠	٢	٢٠	٣	١٠

Test of Goodness of Fit

Maximum Likelihood Method

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Visual Basic

K-S

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Access

Excel

(Spss)

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$x^2$

$H_0$

( , )

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( )

.(  $\hat{\alpha} = 2.41, \hat{\beta} = 9.41$  )

.(  $\hat{\theta} = 3.027$  )

( )

( $m=1,2,3$  )

( $t_c=120\text{day}$  )

$R_{t_c}^{(m)}(t)$

R(t)

( )

جدول (٣)





قيم دالة المعولية للماكنة تحت الدراسة قبل إجراء عملية الفحص وبعدها

m	t	$R_{t_c}^{(m)}$	R(t)
1	5	0.99518	0.80424
	10	0.49	0.31
	15	9.13E-02	4.61E-02
	20	5.34E-03	2.13E-03
	25	8.56E-05	2.66E-05
	30	3.34E-07	7.93E-08
	60	7.10E-37	1.83E-38
	90	7.85E-98	5.41E-101
	120	4.87E-196	2.71E-201
2	150	1.63E-202	0.00
	180	3.46E-232	0.00
	210	3.82E-293	0.00
	240	0.00	0.00

R(t) ( )

( )

( )

( ) ( , )

( )

( , E-08)

$R_{t_c}^{(m)}(t)$  R(t)

$R_{t_c}^{(m)}(t)$

( ) ( , )

( )

(1.63E-202)

(3.34E-07)

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٦. الاستنتاجات

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## ٧. التوصيات

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## المصادر

### المصادر العربية

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### الملحق

: m=1 t<sub>c</sub> t

```
MSFlexGrid1.TextMatrix(0, 0) = "ti"  
MSFlexGrid1.TextMatrix(0, 1) = "Rm"  
MSFlexGrid1.TextMatrix(0, 2) = "R"  
a = InputBox(a1, "operating alfa")  
b = InputBox(b1, "operating beta")  
c = InputBox(c1, "delay time alfa")  
d = InputBox(d1, "delay time beta")  
tf = InputBox(tf1, "time inspection")  
n = InputBox(n1, "division interval")  
m = 1  
X1 = (m - 1) * tf  
X2 = m * tf  
For t = 1 To X2  
h = (t - (m - 1) * tf) / n  
k4 = 0 ' if index is even'  
k5 = 0 ' if index is odd'  
Y1 = 0
```

- ) ( ) ..... .. (



```

For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
Else
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
End If
Next i
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (tf / b) ^ a) 'if index equal n'
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
Text1.Text = integralgy
k8 = Exp(-1 * (tf / b) ^ a) ' integral of g(y)'
Text2.Text = k8
MSFlexGrid1.TextMatrix(t, 2) = k8
rial = Val(Text1.Text) + Val(Text2.Text)
Text3.Text = rial
Text11.Text = Text3.Text
MSFlexGrid1.TextMatrix(t, 1) = Text3.Text
MSFlexGrid1.TextMatrix(t, 0) = t
Next t

```

: m=2 t<sub>c</sub> t - -

```

t = InputBox(t1, "operating time")
a = InputBox(a1, "operating alfa")
b = InputBox(b1, "operating beta")
c = InputBox(c1, "delay time alfa")
d = InputBox(d1, "delay time beta")
tf = InputBox(tf1, "final time")
n = InputBox(n1, "division interval")
m = 2
X1 = (m - 1) * tf
X2 = m * tf

```





```

Print X1, t, X2
If Val(t) > Val(X1) Then
If Val(t) < Val(X2) Then
'comput relilbty with m=1 and t=t-tf
m1 = 1
t2 = t - tf
h = (t2 - (m1 - 1) * tf) / n
k4 = 0 ' if index is even'
k5 = 0 ' if index is odd'
Y1 = 0
For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
Else
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
End If
Next i
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (tf / b) ^ a) 'if index equal n'
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
k8 = Exp(-1 * (t2 / b) ^ a) ' integral of g(y)'
End If
End If
rial = integralgy + k8
Text3.Text = rial
'comput inte(g(y))and integ(g(y)*m(t-y) when m=2 and tf
h = (t - (m - 1) * tf) / n
k4 = 0 ' if index is even'
k5 = 0 ' if index is odd'
Y1 = 0
For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then

```





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k4 = k4 + (Y1 / b) ^ (a - 1) \* Exp(-1 \* (Y1 ^ a \* c ^ d + (t - Y1) ^ d \* b ^ a) / (b ^ a \* c ^ d))

Else

k5 = k5 + (Y1 / b) ^ (a - 1) \* Exp(-1 \* (Y1 ^ a \* c ^ d + (t - Y1) ^ d \* b ^ a) / (b ^ a \* c ^ d))

End If

Next i

k6 = ((m - 1) \* tf / b) ^ (a - 1) \* Exp(-1 \* (((m - 1) \* tf) ^ a \* c ^ d + (t - (m - 1) \* tf) ^ d \* b ^ a) / (b ^ a \* c ^ d)) 'if index equal 0)

k7 = (tf / b) ^ (a - 1) \* Exp(-1 \* (t / b) ^ a) 'if index equal n'

integralgy = ((a \* h) / (3 \* b)) \* (k6 + 4 \* k5 + 2 \* k4 + k7)

Text1.Text = integralgy

k8 = Exp(-1 \* (t / b) ^ a) 'integral of g(y)'

Text2.Text = k8

'compute int(g(y)\*m(j\*tf-y)) when m=2 and tf'

j = 1

h = tf / n

k = 0 'if index is even'

k2 = 0 'if index is odd'

y = 0

For i = 1 To (n - 1)

y = y + h

r = i \ 2

r1 = i - 2 \* r

If r1 = 0 Then

k = k + (y / b) ^ (a - 1) \* Exp(-1 \* (y ^ a \* c ^ d + (j \* tf - y) ^ d \* b ^ a) / (b ^ a \* c ^ d))

Else

k2 = k2 + (y / b) ^ (a - 1) \* Exp(-1 \* (y ^ a \* c ^ d + (j \* tf - y) ^ d \* b ^ a) / (b ^ a \* c ^ d))

End If

Next i

k3 = (j \* tf / b) ^ (a - 1) \* Exp(-1 \* (j \* tf / b) ^ a) 'if index equal tf'

integralgy = ((a \* h) / (3 \* b)) \* (4 \* k2 + 2 \* k + k3)

Text4.Text = integralgy

Text5.Text = Val(Text3.Text) \* Val(Text4.Text) + Val(Text1.Text) + Val(Text2.Text) 'relibilty with m=2 and tf'





Text11.Text = Text5.Text

: m=3 t<sub>c</sub>

t

-

```

t = InputBox(t1, "operating time")
a = InputBox(a1, "operating alfa")
b = InputBox(b1, "operating beta")
c = InputBox(c1, "delay time alfa")
d = InputBox(d1, "delay time beta")
tf = InputBox(tf1, "final time")
n = InputBox(n1, "division interval")
m = 3
X1 = (m - 1) * tf
X2 = m * tf
Print X1, t, X2
If Val(t) > Val(X1) Then
If Val(t) < Val(X2) Then
'comput relilby with m=1 and t=t-2*tf'
m1 = 1
t2 = t - 2 * tf
h = (t2 - (m1 - 1) * tf) / n
k4 = 0 ' if index is even'
k5 = 0 ' if index is odd'
Y1 = 0
For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
Else
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
End If
Next i
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (t2 / b) ^ a) 'if index equal n'
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
k8 = Exp(-1 * (t2 / b) ^ a) ' integral of g(y)'
End If

```



- ) ( ) ..... .. .. (



```

End If
rial = integralgy + k8
Text1.Text = rial
'comput int(g(y)*m(j*tf-y)) when m=3 and tf
j = 1
h = tf / n
k = 0 ' if index is even'
k2 = 0 ' if index is odd'
y = 0
For i = 1 To (n - 1)
y = y + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k = k + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b ^
a * c ^ d))
Else
k2 = k2 + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b
^ a * c ^ d))
End If
Next i
k3 = (j * tf / b) ^ (a - 1) * Exp(-1 * (j * tf / b) ^ a) 'if index equal tf
integralgy = ((a * h) / (3 * b)) * (4 * k2 + 2 * k + k3)
Text2.Text = integralgy
'comput int(g(y)*m(j*tf-y)) when m=3 and tf
j = 2
h = tf / n
k = 0 ' if index is even'
k2 = 0 ' if index is odd'
y = 0
For i = 1 To (n - 1)
y = y + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k = k + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b ^
a * c ^ d))
Else

```





```
k2 = k2 + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b ^ a * c ^ d))
```

```
End If
```

```
Next i
```

```
k1 = ((j - 1) * tf / b) ^ (a - 1) * Exp(-1 * (((j - 1) * tf) ^ a * c ^ d + tf ^ d * b ^ a) / (b ^ a * c ^ d)) 'if index equal 0'
```

```
k3 = (j * tf / b) ^ (a - 1) * Exp(-1 * (j * tf / b) ^ a) 'if index equal tf'
```

```
integralgy = ((a * h) / (3 * b)) * (k1 + 4 * k2 + 2 * k + k3)
```

```
Text3.Text = integralgy
```

```
'compute relilby with m=2 and t=t-tf'
```

```
X1 = (m - 1) * tf
```

```
X2 = m * tf
```

```
Print X1, t, X2
```

```
If Val(t) > Val(X1) Then
```

```
If Val(t) < Val(X2) Then
```

```
'compute relilby with m=1 and t=t-3*tf'
```

```
m1 = 1
```

```
t2 = t - 2 * tf
```

```
h = (t2 - (m1 - 1) * tf) / n
```

```
k4 = 0 'if index is even'
```

```
k5 = 0 'if index is odd'
```

```
Y1 = 0
```

```
For i = 1 To (n - 1)
```

```
Y1 = Y1 + h
```

```
r = i \ 2
```

```
r1 = i - 2 * r
```

```
If r1 = 0 Then
```

```
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) / (b ^ a * c ^ d))
```

```
Else
```

```
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t2 - Y1) ^ d * b ^ a) / (b ^ a * c ^ d))
```

```
End If
```

```
Next i
```

```
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (t2 / b) ^ a) 'if index equal n'
```

```
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
```

```
k8 = Exp(-1 * (t2 / b) ^ a) ' integral of g(y)'
```

```
End If
```

```
End If
```



- ) ( ) ..... .. .. (

```

rial = integralgy + k8
Text4.Text = rial
'compute inte(g(y))and integ(g(y)*m(t-y) when m=2 and tf'
m2 = 2
t3 = t - tf
h = (t3 - (m2 - 1) * tf) / n
k4 = 0 ' if index is even'
k5 = 0 ' if index is odd'
Y1 = 0
For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t3 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
Else
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t3 - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
End If
Next i
k6 = ((m2 - 1) * tf / b) ^ (a - 1) * Exp(-1 * (((m2 - 1) * tf) ^ a * c ^ d + (t3 -
(m2 - 1) * tf) ^ d * b ^ a) / (b ^ a * c ^ d)) 'if index equal 0)
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (t3 / b) ^ a) 'if index equal n'
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
Text1.Text = integralgy
k8 = Exp(-1 * (t3 / b) ^ a) ' integral of g(y)'
Text5.Text = k8
'compute int(g(y)*m(j*tf-y)) when m=2 and tf'
j = 1
h = tf / n
k = 0 ' if index is even'
k2 = 0 ' if index is odd'
y = 0
For i = 1 To (n - 1)
y = y + h
r = i \ 2
r1 = i - 2 * r

```





```

If r1 = 0 Then
k = k + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b ^
a * c ^ d))
Else
k2 = k2 + (y / b) ^ (a - 1) * Exp(-1 * (y ^ a * c ^ d + (j * tf - y) ^ d * b ^ a) / (b
^ a * c ^ d))
End If
Next i
k3 = (j * tf / b) ^ (a - 1) * Exp(-1 * (j * tf / b) ^ a) 'if index equal tf
integralgy = ((a * h) / (3 * b)) * (4 * k2 + 2 * k + k3)
Text6.Text = integralgy
Text7.Text = Val(Text3.Text) * Val(Text4.Text) + Val(Text1.Text) +
Val(Text2.Text) 'relibilty with m=2 and tf
'compute int(g(y) when m=3 and tf
k9 = Exp(-1 * (t / b) ^ a) ' integral of g(y)'
Text8.Text = k9
'compute int(g(y)m(t-y)) when m=3 and tf
m = 3
h = (t - (m - 1) * tf) / n
k4 = 0 ' if index is even'
k5 = 0 ' if index is odd'
Y1 = 0
For i = 1 To (n - 1)
Y1 = Y1 + h
r = i \ 2
r1 = i - 2 * r
If r1 = 0 Then
k4 = k4 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
Else
k5 = k5 + (Y1 / b) ^ (a - 1) * Exp(-1 * (Y1 ^ a * c ^ d + (t - Y1) ^ d * b ^ a) /
(b ^ a * c ^ d))
End If
Next i
k6 = ((m - 1) * tf / b) ^ (a - 1) * Exp(-1 * (((m - 1) * tf) ^ a * c ^ d + (t - (m -
1) * tf) ^ d * b ^ a) / (b ^ a * c ^ d)) 'if index equal 0)
k7 = (tf / b) ^ (a - 1) * Exp(-1 * (t / b) ^ a) 'if index equal n'
integralgy = ((a * h) / (3 * b)) * (k6 + 4 * k5 + 2 * k4 + k7)
Text9.Text = integralgy

```



- ) ( ) ..... .. .. (



```
Text11.Text = Val(Text2.Text) * Val(Text7.Text) + Val(Text3.Text) *  
Val(Text1.Text) + Val(Text8.Text) + Val(Text9.Text)
```

: t R(t) -

```
t = InputBox(t1, "operating time")  
a = InputBox(a1, "operating alfa")  
b = InputBox(b1, "operating beta")
```

```
k13 = Exp(-1 * (t / b) ^ a) ' integral of g(y)'  
Text11.Text = k13
```

