

## **A Decision – Theoretic Bayesian Approach For Selecting the Best of Gamma Populations With General Loss Function**

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### **Abstract**

Statistical selection procedures are used to select the best of a finite set of alternatives. This paper derives a procedure for selecting the best of two Gamma populations employing a decision-theoretic Bayesian framework with general loss function with Exponential prior .

The numerical result of this procedure are given with different loss functions constant , linear and quadratic , where in one equation we can obtain the Bayes risk for the three types of the loss functions : constant , linear and quadratic . in this paper the numerical results are given by using Math Works Matlab ver. 7.0.1 .

Keywords and phrases : selection procedure, general loss function , Bayesian decision theoretic , Exponential prior , Bayes risk .

### **الخلاصة**

تستخدم طرق الاختيار الاحصائية لاختيار الافضل من بين مجموعة محدودة من البدائل . هذا البحث يتضمن اشتقاق طريقة لاختيار الافضل من بين مجتمعين يتوزعان توزيع كاما مستخدمين منهج القرار البيزي مع دالة خسارة مشتركة مع توزيع سابق للتجربة متمثل بالتوزيع الآسي .  
النتائج العددية لهذا الاجراء تم إيجادها لدوال خسارة مختلفة ثابتة ، خطية وتربعية حيث في معادلة واحدة بالامكان الحصول على الخطورة البيزية للأنواع الثلاثة من دوال الخسارة : الثابتة ، الخطية والتربعية . وفي هذا البحث قدمنا نتائج عددية تم الحصول عليها باستخدام نظام الـ Matlab ver 7.0.1 .

### **1-Description of the Problem**

The Gamma distribution has an important role for modeling the life time distribution of a variety of random phenomena . This distribution arises in many areas of application , including reliability , life – testing and survival analysis .

A common problem that arises in practice is the selection of the best of two Gamma populations with unknown parameters .

Formally , we can state the problem as follows : Consider two independent Gamma populations  $\Pi_1, \Pi_2$  with known probability density function

$$h_i(y_i|\alpha_i, \theta_i) = \frac{\theta_i^{\alpha_i}}{\Gamma(\alpha_i)} y_i^{\alpha_i-1} e^{-\theta_i y_i} , y_i > 0 , \alpha_i > 0 , \theta_i > 0$$

With known shape parameter  $\alpha_i$  and unknown scale parameter  $\theta_i$  (i=1,2) . We consider the problem : how to find the best population (i.e. the one associated with the largest scale parameter

$\theta_i$ ) . Let  $\theta_{[1]} \leq \theta_{[2]}$  be the ordered values of the parameters  $\theta_1, \theta_2$  . It is assumed that the exact pairing between the ordered and unordered parameters is unknown . The population  $\Pi_i$  with  $\theta_i = \theta_{[2]} (i=1,2)$  is called the best population . A correct selection is defined as the selection of the population associated with  $\theta_{[2]}$  .

Many researchers have considered this problem under different types of formulations .Shanti S. Gupta (1962) considered the problem of selecting a subset of k Gamma populations which includes the "best" population . P.Vellaisamy , D. Sharma (1988) considered classic procedure for selected Gamma population from two Gamma populations . Neeraj Misra , et.al. (2006) consider selected Gamma population under the scale invariant squared error loss function . Paul Van Der Laan & Constance Van Eden (1996) study the subset selection procedure for studied selecting the Best of Two Gamma population . Neeraj Misra (1994) considered subset selection procedure for selected Gamma populations . Dailami , N. ; Rao , M. Bhaskara ; Subramanyam , K. (1985) study the selection of the best Gamma population , determination of minimax sample size . Studied Nematollahi (2009) estimation of the scale parameter of the selected Gamma population under Entropy loss function .

The aim of this present paper is to derive approach for selecting the best of two Gamma populations , that is the one having the largest scale parameter  $\theta_{[2]}$  by using Bayesian decision – theoretic framework with exponential prior and general loss function .

## **2-Basic Definitions and Concepts**

### **2-1-Statistical Decision Theory**

#### **(i) Basic Ideas**

Statistics may be consider as the science of decision making in the presence of uncertainty . The problems of statistical inferences can fit into the decision theory framework , for example , testing of a hypothesis  $H_0$  against a hypothesis  $H_1$  may be regarded as a decision between two actions (i) accepting  $H_0$  or (ii) accepting  $H_1$  .

In decision problems , the state of nature is unknown , but a decision maker must be made – a decision whose consequences depend on the unknown state of nature . Such a problem is a statistical decision problem when there are data that give partial information a bout the unknown state .

The basic elements of a statistical decision problem can be formalized mathematically as follows:

A set  $A$  , the action space , consisting of all possible actions ,  $a \in A$  , available to the decision maker ;

a set  $\Omega$  , the parameter space , consisting of all possible 'state of the nature' ,  $\theta \in \Omega$  , one and only one of which obtains or will obtain (this 'true' state being unknown to the decision-maker) ;

a function  $L$  , the loss function , having domain  $\Omega \times A$  (the set of all ordered pairs of consequences  $(\theta, a), \theta \in \Omega, a \in A$ ) and codomain  $R$  ;

a set  $R_x$  , the space of  $X$  , consisting of all the possible realizations ,  $x \in R_x$  of a random variable  $X$  , having a distribution whose probability function (pf) belongs to a specified family  $\{f(x; \theta); \theta \in \Omega\}$  ;

A set  $D$  , the decision space, consisting of all possible decisions ,  $d \in D$  , each such decision function  $d$  having domain  $R_x$  and codomain  $A$  .

**(ii) The Risk Function**

For given  $(\theta, a)$  the loss function depends on the outcome  $x$  and thus a random variable . Its expected value , i.e. its average over all possible outcomes is called the risk function and is denoted by

$$R(\theta, d) = \int_{R_x} L(\theta, d(x))f(x; \theta)dx \quad (\text{X continues})$$

or

$$R(\theta, d) = \sum_{x \in R_x} L(\theta, d(x))f(x; \theta) \quad (\text{X discrete})$$

**(iii) Minimax and Bayes Decision Functions**

The decision function  $d^*$  that minimizes  $M(d) = \max R(\theta, d)$  is the minimax decision function . Similarly , the function  $d^{**}$  that minimizes the Bayes risk of a decision  $d$  is a Bayes decision function .

$$B(d) = E[R(\theta, d)] = \int_{\Theta} R(\theta, d)\pi(\theta)d\theta \quad (\Theta \text{ continuous})$$

or

$$B(d) = \sum_{\Theta} R(\theta, d)\pi(\theta) \quad (\Theta \text{ discrete})$$

where  $\pi(\theta)$  represents the distribution of degree of belief over  $\Theta$  .

**3- Solution of the Problem**

We term our problem as a two-decision problem and represent it symbolically as

$$d_1 : \text{population } \Pi_1 \text{ is said to be the best if } \theta_1 > \theta_2$$

and .....(2-1)

$$d_2 : \text{population } \Pi_2 \text{ is said to be the best if } \theta_1 \leq \theta_2$$

For parameter  $\theta$  and action  $a$  the loss function is defined as :

$$L_i(\theta_i, a_i) = k_i(\theta_i - a_i)^r, i = 1, 2, \dots \dots \dots (2-2)$$

For  $r=0$  , we have a constant loss function , for  $r=1$  , we have a linear loss function and for  $r=2$  , we have a quadratic loss function ,  $k_1, k_2$  give decision losses in units of costs .

Let us suppose that  $y_i = (y_{i1}, y_{i2}, \dots, y_{in})$  be a random sample of size  $n$  arising from population  $\Pi_i$  . It follows that the likelihood function is

$$P_o(y|\theta_i) = \left( \frac{\theta_i^{\alpha_i}}{\Gamma(\alpha_i)} \right)^n e^{-\theta_i \sum_{j=1}^n y_{ij}} \prod_{j=1}^n y_{ij}^{\alpha_i-1}, \quad \theta_i > 0, y > 0, \alpha_i > 0, \dots\dots\dots(2-3)$$

Our first task in the Bayesian approach is the specification of a prior p.d.f  $g(\lambda)$  . we take the prior distribution to be a member of the conjugate class of Exponential priors  $Exp(\lambda_i)$ , where a member of this class has density function

$$g(\theta_i|\lambda_i) = \lambda_i e^{-\lambda_i \theta_i}, \quad \lambda_i > 0, \theta_i > 0 \dots\dots\dots(2-4)$$

By Baye's theorem the posterior probability function of  $\theta$  is given by

$$g(\theta_i|y_{-i}) = \lambda_i' e^{-\theta_i \lambda_i'} \dots\dots\dots(2-5)$$

Where  $\lambda_i' = \sum_{j=1}^n y_{ij} + \lambda_i$  ,  $i = 1,2$

We note , as a function of  $\theta_i$  ,  $g(\theta_i|y_{-i})$  has the form of Exponential probability density

function with parameters  $\lambda_i'$  .

We derive the stopping (Baye's) risks of decision  $d_1$  and  $d_2$  for general loss function given in (2-2) and the stopping risk (the posterior expected losses) of making decision  $d_i$  denoted by  $R_i(\theta_1, \theta_2; d_i)$

$$R_1(\theta_1, \theta_2; d_1) = k_1 \left[ \sum_{i=0}^r \frac{r!(-1)^{r-i}}{(\lambda_2')^{r-i} (\lambda_1')^i} - \sum_{i=0}^r \sum_{j=0}^{r-i} \frac{r!(-1)^{r-i} \lambda_1' (\lambda_2')^{-j} (r-j)!}{i!(r-i-j)! (\lambda_1' + \lambda_2')^{r-j+1}} \right]$$

$$R_2(\theta_1, \theta_2; d_2) = k_2 \left[ \sum_{i=0}^r \frac{r!(-1)^{r-i}}{(\lambda_1')^{r-i} (\lambda_2')^i} - \sum_{i=0}^r \sum_{j=0}^{r-i} \frac{r!(-1)^{r-i} \lambda_2' (\lambda_1')^{-j} (r-j)!}{i!(r-i-j)! (\lambda_1' + \lambda_2')^{r-j+1}} \right]$$

If we take  $r=0$  we find from the above equations the posterior expected losses for constant loss function for the two decisions  $d_1$  and  $d_2$  , if we take  $r=1$  we find from the above equations the posterior expected losses for linear loss function for the two decisions , if we take  $r=2$  we find from the above equations the posterior expected losses for quadratic loss function for two decision  $d_1$  and  $d_2$  .

For the two – decision problem considered a above , the Bayesian selection procedure is given as follows :

Make decision  $d_1$  that is selecting  $\Pi_1$  as the best population if  $R_1(\theta_1, \theta_2; d_1) < R_2(\theta_1, \theta_2; d_2)$

and

Make decision  $d_2$  that is selecting  $\Pi_2$  as the best population if  $R_1(\theta_1, \theta_2; d_1) \geq R_2(\theta_1, \theta_2; d_2)$

**4- Numerical Results and Discussions**

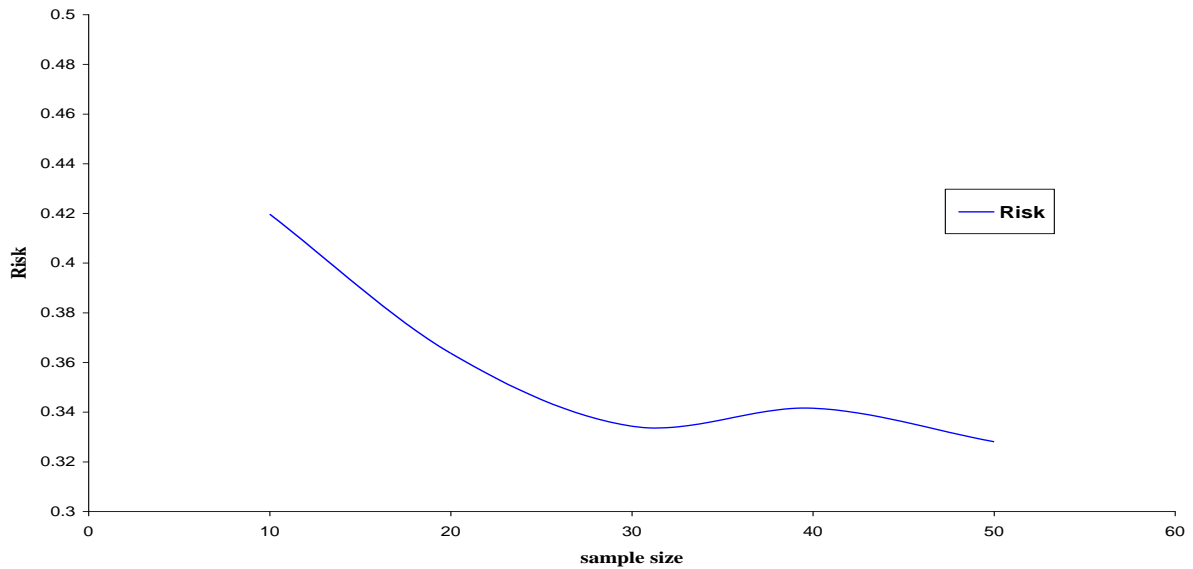
This section contains some numerical result about this procedure , we take various sample size n and various priors . We write a program for this procedure from which we give three types of Risk for three types of loss functions (constant , linear and quadratic) . from this numerical result we note that :

- 1-the procedure is well defined , as we seen in table (1) .
- 2-as sample size n increase , the Bayes risk decreases .
- 3-The Bayes risk for quadratic loss function is less than the Bayes risk for linear and constant loss functions .

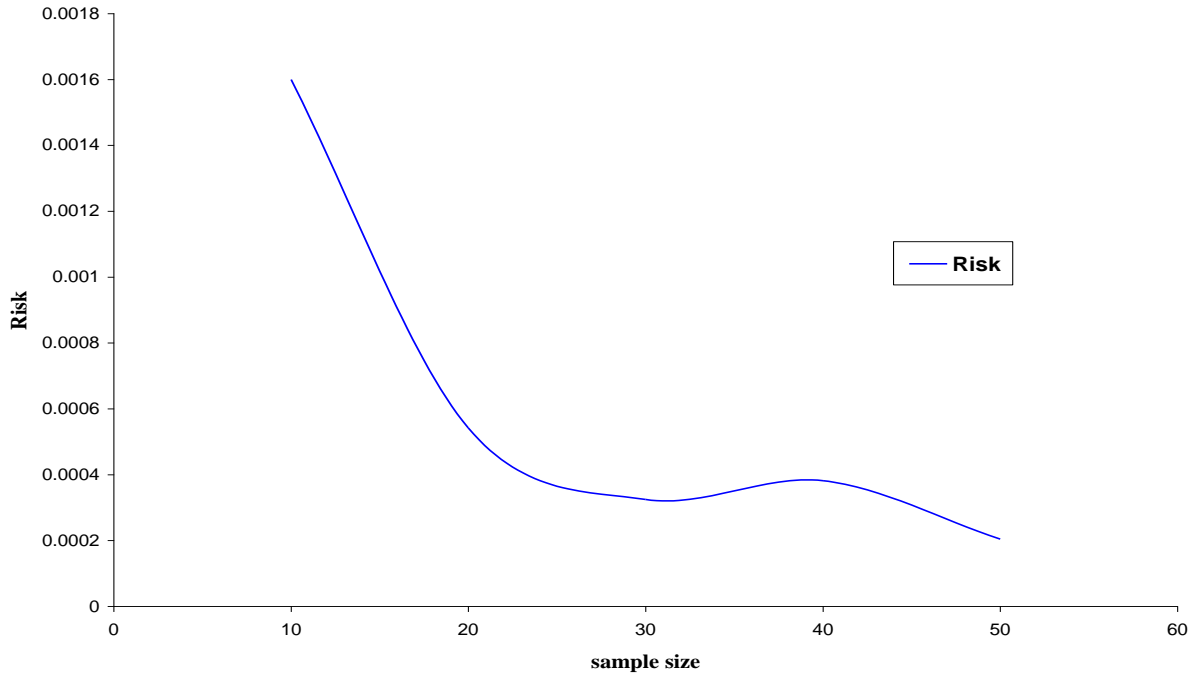
$\theta_1 = 10, \theta_2 = 2, \alpha_1 = \alpha_2 = 3$						
Prior Prob. ( $\lambda_1, \lambda_2$ )	n	Bayes Risk	Constant Loss	Linear Loss	Quadratic Loss	
(4,7)	10	R(d <sub>1</sub> )	0.4197	0.0016	2.0194e-005	
		R(d <sub>2</sub> )	1.5803	0.0183	8.3546e-004	
	20	R(d <sub>1</sub> )	0.3637	5.4201e-041	2.4397e-006	
		R(d <sub>2</sub> )	1.6363	0.0111	1.4006e-004	
	30	R(d <sub>1</sub> )	0.3343	3.2460e-004	6.4979e-007	
		R(d <sub>2</sub> )	1.6657	0.0086	1.0006e-004	
	40	R(d <sub>1</sub> )	0.3416	3.8191e-004	6.2400e-007	
		R(d <sub>2</sub> )	1.6584	0.0055	6.8677e-005	
	50	R(d <sub>1</sub> )	0.3281	2.0458e-004	4.3678e-007	
		R(d <sub>2</sub> )	1.6719	0.0048	2.3776e-005	
	(6,10)	10	R(d <sub>1</sub> )	0.4522	9.5929e-004	1.7892e-005
			R(d <sub>2</sub> )	1.5478	0.0222	3.9764e-004
20		R(d <sub>1</sub> )	0.3402	3.9715e-0051	4.4915e-006	
		R(d <sub>2</sub> )	1.6598	0.0137	1.4732e-004	
30		R(d <sub>1</sub> )	0.3295	4.4710e-004	1.2465e-006	
		R(d <sub>2</sub> )	1.6705	0.0077	9.4003e-005	
40		R(d <sub>1</sub> )	0.3388	2.6590e-004	4.6549e-007	
		R(d <sub>2</sub> )	1.6612	0.0071	8.2271e-005	
50		R(d <sub>1</sub> )	0.2911	1.8176e-004	2.5639e-007	
		R(d <sub>2</sub> )	1.7089	0.0059	2.6276e-005	
(8,12)		10	R(d <sub>1</sub> )	0.4474	7.2249e-004	3.8048e-006
			R(d <sub>2</sub> )	1.5526	0.0220	5.1106e-004
	20	R(d <sub>1</sub> )	0.3379	4.2249e-0041	1.4942e-006	
		R(d <sub>2</sub> )	1.6621	0.0123	1.9099e-004	
	30	R(d <sub>1</sub> )	0.3890	2.9478e-004	9.1622e-007	
		R(d <sub>2</sub> )	0.3546	0.0089	6.5576e-005	
	40	R(d <sub>1</sub> )	0.3546	2.4135e-004	3.8832e-007	
		R(d <sub>2</sub> )	1.6454	0.0069	4.5099e-005	

(10,14)	50	R(d <sub>1</sub> )	0.3458	1.6914e-004	2.1242e-007
		R(d <sub>2</sub> )	1.6542	0.0053	2.9020e-005
	10	R(d <sub>1</sub> )	0.4164	0.0022	7.9105e-006
		R(d <sub>2</sub> )	1.5836	0.0146	4.5275e-004
	20	R(d <sub>1</sub> )	0.3864	5.0357e-004	2.5672e-006
		R(d <sub>2</sub> )	1.6136	0.0155	1.7845e-004
	30	R(d <sub>1</sub> )	0.3943	4.0063e-004	1.1416e-006
		R(d <sub>2</sub> )	1.6057	0.0077	1.0671e-004
	40	R(d <sub>1</sub> )	0.3683	3.0555e-004	7.3245e-007
		R(d <sub>2</sub> )	1.6317	0.0061	5.0115e-005
	50	R(d <sub>1</sub> )	0.3177	1.4337e-004	2.9984e-007
		R(d <sub>2</sub> )	1.6823	0.0062	3.5540e-005

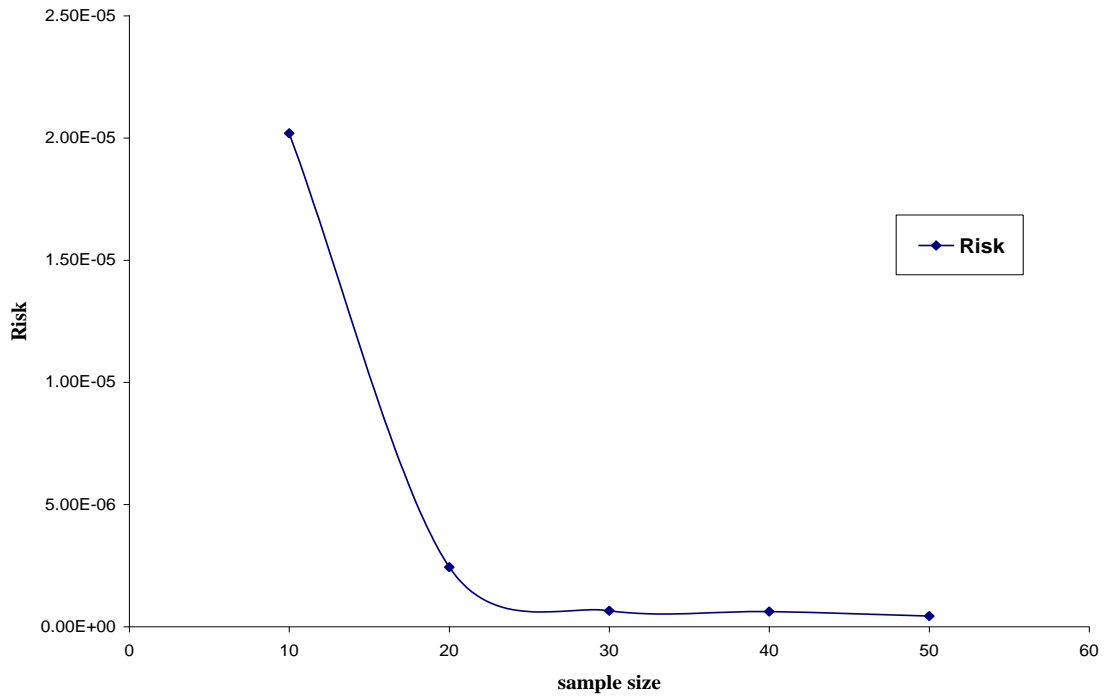
**Table (1)**



**Figure (1) : the influence of the sample size on the posterior expected loss for constant loss function**



**Figure (2) : the influence of the sample size on the posterior expected loss for linear loss function**



**Figure (3) : the influence of the sample size on the posterior expected loss for quadratic loss function**

## **Conclusions**

In this paper we derives a procedure for selecting the best of two Gamma populations employing a decision – theoretic Bayesian frame work with general loss function with Exponential prior . From this paper we note that :

- 1- the procedure is well defined , as we seen in table (1)
- 2- as sample size  $n$  increase , the Bayes risk decreases with all loss functions .
- 3- the Bayes risk for quadratic loss function is less than the Bayes risk for linear and constant loss function .

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