Differentiation of the Al-Tememe Transformation And Solving Some Linear Ordinary Differential Equation With or Without Initial Conditions مشتقة تحويل التميمي وحل بعض المعادلات التفاضلية الخطية الاعتيادية الخاضعة و غير مشتقة تحويل التميمي وحل بعض المعادلات التفاضلية الخطية الاعتيادية الخاضعة و غير prof.Ali Hassan Mohammed/** Alaa Sallh Hadi/*** Hassan Nadem Rasoul *** University of Kufa. Faculty of Education of Women. Department of Mathematics *** University of Kufa. Faculty of Computer Science and Math. Department of Mathematics The exact competence: Differential equations **Aass85@yahoo.com **alaasalh.hadi@gmail.com ***Hassan.nadem.rasoul@gmail.com

Abstract:

Our aim in this paper is to find the derivative of Al-<u>Tememe</u> transformation and to find Al-Tememe transformation by using derivative for new functions and to use it to solve some Linear Ordinary Differential Equation that have variable coefficients with or without initial conditions.

المستخلص: هدفنا في هذا البحث هو ايجاد المشتقة لتحويل التميمي وايجاد تحويل التميمي لدوال جديدة بأستخدام المشتقة وايجاد حل المعادلات التفاضلية الاعتيادية الخطية ذات المعاملات المتغيرة الخاضعة وغير الخاضعة لشروط ابتدائية_.

Introduction:

Laplace transform [3] is an important method for solving ODEs with constant coefficients under initial conditions.

The Al-Tememe transform [4] began at 2008 by prof A.H.Mohammed, this transform used to solve ordinary differential equation with variable coefficients with initial conditions. We will use the idea which exist at [3] to solve ODEs contains the terms $(ln x)^n$ and $[x^m (ln x)^n]$; where $m, n \in \mathbb{N}$ by using Al-Tememe transform.

Basic definitions and concepts :

Definition 1: [2]

Let f is defined function at a period (a, b) then the integral transformation for f whose it's symbol F(p) is defined as :

$$F(p) = \int_{a}^{b} k(p, x) f(x) dx$$

Where *k* is a fixed function of two variables, which is called the kernel of the transformation, and *a*, *b* are real numbers or $\mp \infty$, such that the integral above convergent. **Definition 2:** [4]

The Al-Tememe transformation for the function f(x); x > 1 is defined by the following integral :

$$\mathcal{T}[f(x)] = \int_{1}^{\infty} x^{-p} f(x) dx = F(p)$$

Such that this integral is convergent, p positive is constant.

Property 1: [4]

Al-Tememe transformation is characterized by the linear property, that is:

 $\mathcal{T}[Af(x) + Bg(x)] = A\mathcal{T}[f(x)] + B\mathcal{T}[g(x)],$

Where A, B are constants, the functions f(x), g(x) are defined when x > 1. The Al-Tememe transform of some fundamental functions are given in table(1) [4]:

ID	Function, $f(x)$	$F(p) = \int_{1}^{\infty} x^{-p} f(x) dx$ $= \mathcal{T}[f(x)]$	Regional of convergence
1	k; k = constant	$\frac{k}{p-1}$	<i>p</i> > 1
2	x^n , $n \in R$	$\frac{1}{p - (n + 1)}$	p > n+1
3	ln x	$\frac{1}{(p-1)^2}$	<i>p</i> > 1
4	$x^n \ln x$, $n \in R$	$\frac{1}{[p-(n+1)]^2}$	p > n+1
5	sin (a ln x)	$\frac{a}{(p-1)^2 + a^2}$	<i>p</i> > 1
6	cos (a ln x)	$\frac{p-1}{(p-1)^2+a^2}$	<i>p</i> > 1
7	sinh (a ln x)	$\frac{a}{(p-1)^2 - a^2}$	p-1 > a
8	cosh (a ln x)	$\frac{p-1}{(p-1)^2-a^2}$	p-1 > a

Table (1).

From the Al-Tememe definition and the above table, we get:

Theorem 1:

If $\mathcal{T}[f(x)] = F(p)$ and *a* is constant, then $\mathcal{T}[x^{-a}f(x)] = F(p+a)$.see [4] *Definition 3:* [4]

Let f(x) be a function where (x > 1) and $\mathcal{T}[f(x)] = F(p), f(x)$ is said to be an inverse for the Al-Tememe transformation and written as $\mathcal{T}^{-1}[F(p)] = f(x)$, where \mathcal{T}^{-1} returns the transformation to the original function.

Property 2: [4]

If $\mathcal{T}^{-1}[F_1(p)] = f_1(x)$, $\mathcal{T}^{-1}[F_2(p)] = f_2(x), \dots, \mathcal{T}^{-1}[F_n(p)] = f_n(x)$ and a_1, a_2, \dots, a_n are constants then,

 $\mathcal{T}^{-1}[a_1F_1(p) + a_2F_2(p) + \dots + a_nF_n(p)] = a_1f_1(x) + a_2f_2(x) + \dots + a_nf_n(x)$ Definition 4: [5]

The

$$a_0 x^n \frac{d^n y}{dx^n} + a_1 x^{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + a_{n-1} x \frac{dy}{dx} + a_n y = f(x),$$

equation

Where $a_0, a_1, ..., a_n$ are constants and f(x) is a function of x, is called *Euler's equation*. *Theorem* 2: [4]

If the function f(x) is defined for x > 1 and its derivatives $f'(x), f''(x), \dots, f^{(n)}(x)$ are exist then:

$$\mathcal{T}[x^n f^{(n)}(x)] = -f^{(n-1)}(1) - (p-n)f^{(n-2)}(1) - \dots - (p-n)(p-(n-1))\dots(p-2)f(1) + (p-n)!F(p)$$

We will use Theorem(2) to prove that

The second case: If n = 2 To find $\mathcal{T}[x^m (\ln x)^2]$ If $m = 1 \implies \mathcal{T}[x(\ln x)^2]$ Consider, $y = x(\ln x)^2 \implies y(1) = 0$ $y' = x \cdot 2(\ln x) \cdot \frac{1}{x} + (\ln x)^2 \implies xy' = 2x(\ln x) + x(\ln x)^2$ $\mathcal{T}(xy') = 2\mathcal{T}[x(\ln x)] + \mathcal{T}(y) = 2 \cdot \frac{1}{(p-2)^2} + \mathcal{T}(y)$ $\therefore \mathcal{T}(xy') = (p-1)\mathcal{T}(y) \implies (p-1)\mathcal{T}(y) = \frac{2}{(p-2)^2} + \mathcal{T}(y)$ $\implies (p-2)\mathcal{T}(y) = \frac{2}{(p-2)^2} \implies \mathcal{T}[x(\ln x)^2] = \frac{2}{(p-2)^3}$(4)

If $m = 2 \implies \mathcal{T}[x^2 (\ln x)^2]$ Consider, $y = x^2 (\ln x)^2 \implies y(1) = 0$ $y' = x^2 \cdot 2(\ln x) \cdot \frac{1}{x} + 2x(\ln x)^2 \implies xy' = 2x^2(\ln x) + 2x^2(\ln x)^2$ $\mathcal{T}(xy') = 2\mathcal{T}[x^2(\ln x)] + 2\mathcal{T}(y) = 2 \cdot \frac{1}{(n-3)^2} + 2\mathcal{T}(y)$ $: \mathcal{T}(xy') = (p-1)\mathcal{T}(y) \implies (p-1)\mathcal{T}(y) = \frac{2}{(p-3)^2} + 2\mathcal{T}(y)$ $\Rightarrow (p-3)\mathcal{T}(y) = \frac{2}{(p-3)^2} \quad \Rightarrow \mathcal{T}[x^2 \ (\ln x)^2] = \frac{2}{(p-3)^3}$...(5) If $m = 3 \implies \mathcal{T}[x^3 (\ln x)^2]$ Consider, $y = x^3 (\ln x)^2$ \Rightarrow y(1) = 0 $y' = x^3 \cdot 2(\ln x) \cdot \frac{1}{x} + 3x^2(\ln x)^2 \implies xy' = 2x^3(\ln x) + 3x^3(\ln x)^2$ $\mathcal{T}(xy') = 2\mathcal{T}[x^3(\ln x)] + 3\mathcal{T}(y) = 2 \cdot \frac{1}{(n-4)^2} + 3\mathcal{T}(y)$ $(p-1)\mathcal{T}(y) = 2 \cdot \frac{1}{(p-4)^2} + 3\mathcal{T}(y) \Longrightarrow \mathcal{T}[x^3 (\ln x)^2] = \frac{2}{(p-4)^3}$...(6) $\mathcal{T}[x^m (\ln x)^2] \quad ; m \in \mathbb{N} \quad \Rightarrow y = x^m (\ln x)^2 \qquad \Rightarrow y(1) = 0$ $y' = x^m \cdot 2(\ln x) \cdot \frac{1}{x} + mx^{m-1}(\ln x)^2 \implies xy' = 2x^m(\ln x) + mx^m(\ln x)^2$ $\mathcal{T}(xy') = 2\mathcal{T}[x^{m}(\ln x)] + m\mathcal{T}(y) = 2 \cdot \frac{1}{[n - (m+1)]^{2}} + m\mathcal{T}(y)$ $(p-1)\mathcal{T}(y) = 2 \cdot \frac{1}{[p-(m+1)]^2} + m\mathcal{T}(y)$ $\Rightarrow \mathcal{T}[x^m (\ln x)^2] = \frac{2!}{[p - (m+1)]^3} \quad ; m \in \mathbb{N}$...(m)*Note*: These cases are also true for $m \in \mathbb{Q}$ **The third case:** To find $\mathcal{T}[x^m (\ln x)^3]$ If $m = 1 \Longrightarrow \mathcal{T}[x(\ln x)^3]$ $\Rightarrow y(1) = 0$ Consider, $y = x(\ln x)^3$ $y' = x \cdot 3(\ln x)^2 \cdot \frac{1}{x} + (\ln x)^3 \implies xy' = 3x(\ln x)^2 + x(\ln x)^3$ $\mathcal{T}(xy') = 3\mathcal{T}[x(\ln x)^2] + \mathcal{T}(y) = 3 \cdot \frac{2}{(n-2)^3} + \mathcal{T}(y)$ $\Rightarrow (p-1)\mathcal{T}(y) = \frac{3!}{(p-2)^3} + \mathcal{T}(y)$ $\Rightarrow (p-2)\mathcal{T}(y) = \frac{3!}{(p-2)^3} \quad \Rightarrow \mathcal{T}[x \ (\ln x)^2] = \frac{3!}{(p-2)^4}$...(7) If $m = 2 \implies \mathcal{T}[x^2(\ln x)^3]$ Consider, $y = x^2 (\ln x)^3 \implies y(1) = 0$ $y' = x^2 \cdot 3(\ln x)^2 \cdot \frac{1}{x} + 2x(\ln x)^3 \Longrightarrow xy' = 3x^2(\ln x)^2 + 2x^2(\ln x)^3$ $\mathcal{T}(xy') = 3\mathcal{T}[x^2(\ln x)^2] + 2\mathcal{T}(y) = 3 \cdot \frac{2}{(n-3)^3} + 2\mathcal{T}(y)$

$$\mathcal{T}[x^{m} (\ln x)^{n}] = \frac{n!}{[p - (m+1)]^{n+1}} ; m \in \mathbb{N} , n \in \mathbb{N}$$

Definition 5: [3] : A function *f* has exponential order α if there exist constants M > 0 and α such that for some $x_0 \ge 0$

$$|f(x)| \le M e^{\alpha x}, \qquad x \ge x_0.$$

Definition 6: [6]

A function f(x) is piecewise continuous on an interval [a, b] if the interval can be partitioned by a finite number of points $a = x_0 < x_1 < \cdots < x_n = b$ such that:

1. f(x) is continuous on each subinterval (x_i, x_{i+1}) , for i = 0, 1, 2, ..., n-1

2. The function f has jump discontinuity at x_i , thus

$$\left|\lim_{x \to x_i^+} f(x)\right| < \infty, i = 0, 1, 2, ..., n-1; \left|\lim_{x \to x_i^-} f(x)\right| < \infty, \quad i = 0, 1, 2, ..., n$$

Note: A function is piecewise continuous on $[0, \infty)$ if it is piecewise continuous in [0, a] for all a > 0

Differentiation of the Laplace Transform [1]

Let f be piecewise continuous function on $[0, \infty)$ of exponential order α and $\mathcal{L}[f(x)] = F(p)$ then:

$$\frac{d^n}{dp^n}F(p) = \mathcal{L}[(-1)^n x^n f(x)] \; ; \; n = 1,2,3, \dots \; (p > \alpha)$$

Differentiation of Al-Tememe transformation

Theorem 3: Let f be piecewise continuous function on $[1,\infty)$ of order α and $\mathcal{T}[f(x)] =$ F(p) then:

 $\frac{a^n}{dp^n} \mathcal{T}[f(x)] = (-1)^n \mathcal{T}[(\ln x)^n f(x)] ; n = 1, 2, 3, \dots (p > \alpha)$ **Proof:** $\mathcal{T}[f(x)] = \int_{1}^{\infty} x^{-p} f(x) dx$ $\Rightarrow \frac{d}{dp}\mathcal{T}[f(x)] = \frac{d}{dp} \int_{1}^{\infty} x^{-p} f(x) dx = \int_{1}^{\infty} \frac{\partial}{\partial p} x^{-p} f(x) dx$ *Note*: $\frac{\partial}{\partial p}x^{-p}$; x constant = $-x^{-p} \ln x$ $= \int_{1}^{\infty} (-x^{-p} \ln x) f(x) dx = (-1)^{1} \int_{1}^{\infty} \ln x \cdot x^{-p} f(x) dx$ Hence

$$\frac{d}{dp}\mathcal{T}[f(x)] = (-1)^{1}\mathcal{T}[\ln x \cdot f(x)] \qquad \dots (10)$$

Also,

$$\frac{d^2}{dp^2} \mathcal{T}[f(x)] = \frac{d}{dp} \left[\frac{d}{dp} \mathcal{T}[f(x)] \right] = \frac{d}{dp} \left[(-1)^1 \mathcal{T}[\ln x \cdot f(x)] \right]$$

$$= (-1)^1 \frac{d}{dp} \int_1^{\infty} \ln x \cdot x^{-p} f(x) dx$$

$$= (-1)^1 \int_1^{\infty} \frac{\partial}{\partial p} x^{-p} \cdot \ln x \cdot x^{-p} f(x) dx$$

$$= (-1)^1 \int_1^{\infty} (-x^{-p} \ln x) \cdot \ln x \cdot f(x) dx$$

$$= (-1)^2 \int_1^{\infty} (\ln x)^2 \cdot x^{-p} f(x) dx$$
So,
$$\frac{d^2}{dp^2} \mathcal{T}[f(x)] = (-1)^2 \mathcal{T}[(\ln x)^2 \cdot f(x)] \qquad \dots (11)$$
And so,on

$$\frac{d^{n}}{dp^{n}}\mathcal{T}[f(x)] = (-1)^{n-1} \int_{1}^{\infty} \frac{\partial}{\partial p} (\ln x)^{n-1} \cdot x^{-p} \cdot f(x) dx$$

$$= (-1)^{n-1} \int_{1}^{\infty} (\ln x)^{n-1} (-1 \cdot x^{-p} \cdot \ln x) f(x) dx$$

$$= (-1)^{n} \int_{1}^{\infty} (\ln x)^{n} \cdot x^{-p} \cdot f(x) dx$$

$$= (-1)^{n} \mathcal{T}[(\ln x)^{n} \cdot f(x)] \qquad \dots (n)$$

$$\frac{d^{n}}{dp^{n}} \mathcal{T}[f(x)] = (-1)^{n} \mathcal{T}[(\ln x)^{n} f(x)] ; n = 1, 2, 3, \dots (p > \alpha) \bullet.$$

$$\Rightarrow \mathcal{T}[(\ln x)^{n} f(x)] = (-1)^{n} \frac{d^{n}}{dp^{n}} \mathcal{T}[f(x)] \; ; \; n = 1, 2, 3, (p > \alpha)$$

Example 1: To find $\mathcal{T}[x^{-3} \ln x]$ we note that

$$\mathcal{T}[\ln x \cdot x^{-3}] = (-1)^1 \frac{d}{dp} \mathcal{T}(x^{-3})$$
$$= -\frac{d}{dp} \cdot \left(\frac{1}{p+2}\right) = \frac{1}{(p+2)^2}$$

By using the previous conversion table

$$\mathcal{T}[\ln x \cdot x^{-3}] = \mathcal{T}[x^{-3} \cdot \ln x] = \frac{1}{(p+2)^2}$$

Example 2: To find $\mathcal{T}[ln x. sin(3ln x)]$ by applying the above relationship:

$$\mathcal{T}[\ln x. \sin 3\ln x] = (-1)^{1} \frac{d}{dp} \left[\frac{3}{(p-1)^{2}+9} \right]$$
$$= \frac{-3 \cdot \{-2(p-1)\}}{[(p-1)^{2}+9]^{2}} = \frac{6(p-1)}{[(p-1)^{2}+9]^{2}}$$

Example 3: To find $\mathcal{T}[ln x . cosh (5ln x)]$ by applying the above relationship:

$$\begin{aligned} \mathcal{T}[\ln x \cdot \cosh (5\ln x)] &= \frac{-d}{dp} \left[\frac{(p-1)}{(p-1)^2 - 25} \right] \\ &= -\frac{[(p-1)^2 - 25] - (p-1) \cdot 2(p-1)}{[(p-1)^2 - 25]^2} \\ &= \frac{p^2 - 2p + 26}{[(p-1)^2 - 25]^2} = \frac{(p-1)^2 + 25}{[(p-1)^2 - 25]^2} \end{aligned}$$

Differential Equations with Polynomial Coefficients by using Laplace Transform .[3].

 $\mathcal{L}[xf(x)] = -F'(p),$ $\mathcal{L}[xf'(x)] = -pF'(p) - F(p),$ $\mathcal{L}[xf''(x)] = -p^2F'(p) - 2pF(p) + y(0)$ Differential Equations with multiple of polym

Differential Equations with multiple of polynomial and logarithms coefficients by using Al-Tememe Transform: Recall (Theorem) that for $E(n) = \mathcal{T}[f(n)]$

$$\frac{d^{n}}{dp^{n}}\mathcal{T}[f(x)] = (-1)^{n}\mathcal{T}[(\ln x)^{n}f(x)] ; n = 1,2,3, \dots (p > \alpha)$$

For a piecewise continuous function f(x) on $[1, \infty)$ and of exponential order α . Hence, for n = 1

$$\mathcal{T}[\ln x \cdot y'] = \frac{-d}{dp} \mathcal{T}(y')$$
$$\mathcal{T}[\ln x \cdot xy'] = \frac{-d}{dp} \mathcal{T}(xy')$$
$$= \frac{-d}{dp} [-y(1) + (p-1)\mathcal{T}(y)]$$
$$= -[(p-1)\mathcal{T}'(y) + \mathcal{T}(y)]$$
$$\mathcal{T}[\ln x \cdot xy'] = -(p-1)\mathcal{T}'(y) - \mathcal{T}(y)$$

Similarly, for

$$\mathcal{T}[\ln x \cdot x^2 y''] = -\frac{d}{dp} [-y'(1) - (p-2)y(1) + (p-1)(p-2)\mathcal{T}(y)]$$
$$= -[-y(1) + (p-2)(p-1)\mathcal{T}'(y) + (2p-3)\mathcal{T}(y)]$$

$$\mathcal{T}[\ln x \, x^2 y''] = y(1) - (p-2)(p-1)\mathcal{T}'(y) - (2p-3)\mathcal{T}(y).$$

In many cases these formulas for $\mathcal{T}[\ln x \cdot xy']$ and $\mathcal{T}[\ln x \cdot x^2y'']$ are useful to solve linear differential equations with variable coefficients.

Example **4***:* To solve the differential equation:

$$x \ln x. y' - y = (\ln x)^{2}$$

By taking (T) to both sides we get:
$$\mathcal{T}[x \ln x. y'] - \mathcal{T}(y) = \mathcal{T}[(\ln x)^{2}]$$
$$-(p-1)\mathcal{T}'(y) - \mathcal{T}(y) - \mathcal{T}(y) = \frac{2!}{(p-1)^{3}}$$
$$-(p-1)\mathcal{T}'(y) - 2\mathcal{T}(y) = \frac{2}{(p-1)^{3}}$$
$$\Rightarrow \mathcal{T}'(y) + \frac{2}{p-1}\mathcal{T}(y) = \frac{-2}{(p-1)^{4}}$$
This is an ordinary linear differential equation and its integrat

This is an ordinary linear differential equation and its integrating factor is given by: $\mu = e^{\int \frac{2}{p-1}dp} = e^{2\ln(p-1)} = e^{\ln(p-1)^2} = (p-1)^2$ Therefore,

$$\begin{aligned} [\mathcal{T}(y).(p-1)^2]' &= \frac{-2}{(p-1)^2} \\ \text{And} \\ \mathcal{T}(y).(p-1)^2 &= -2 \int \frac{1}{(p-1)^2} dp \\ \mathcal{T}(y).(p-1)^2 &= -2.\frac{-1}{(p-1)} + c \\ \mathcal{T}(y) &= \frac{2}{(p-1)^3} + \frac{c}{(p-1)^2} \\ \text{By taking } \mathcal{T}^{-1} \text{ to both sides we get :} \\ y &= \mathcal{T}^{-1} \left[\frac{2}{(p-1)^3} \right] + \mathcal{T}^{-1} \left[\frac{c}{(p-1)^2} \right] \\ y &= (\ln x)^2 + c\ln x \ ; \ c \text{ constant} \end{aligned}$$

Example 5: To solve the differential equation: $ln x \cdot x^2 y'' + xy' = xln x$; y(1) = 1

By taking (*T*) to both sides we get:

$$\mathcal{T}(\ln x. x^2 y'') + \mathcal{T}(xy') = \mathcal{T}(x\ln x)$$

$$y(1) - (p-2)(p-1)\mathcal{T}'(y) - (2p-3)\mathcal{T}(y) - y(1) + (p-1)\mathcal{T}(y) = \frac{1}{(p-2)^2}$$

$$-(p-2)(p-1)\mathcal{T}'(y) - (2p-3-p+1)\mathcal{T}(y) = \frac{1}{(p-2)^2}$$

$$-(p-2)(p-1)\mathcal{T}'(y) - (p-2)\mathcal{T}(y) = \frac{1}{(p-2)^2}$$

$$\mathcal{T}'(y) + \frac{1}{p-1}\mathcal{T}(y) = \frac{-1}{(p-2)^3(p-1)}$$
This is an endingenvised set of the provided matrix is the provided matrix.

This is an ordinary linear differential equation and its integrating factor is given by:

$$\mu = e^{\int \frac{1}{p-1} dp} = e^{\ln(p-1)} = (p-1)$$

Therefore,

$$\begin{aligned} [\mathcal{T}(y).(p-1)]' &= \frac{-1}{(p-2)^3} \\ \Rightarrow \mathcal{T}(y).(p-1) &= \int \frac{-1}{(p-2)^3} dp \\ &= \frac{1}{2(p-2)^2} + \mathcal{C} \\ \mathcal{T}(y) &= \frac{1}{2(p-2)^2(p-1)} + \frac{\mathcal{C}}{(p-1)} \\ \frac{1}{2(p-2)^2(p-1)} &= \frac{A}{p-2} + \frac{B}{(p-2)^2} + \frac{\mathcal{C}}{p-1} \\ &= \frac{-1/2}{p-2} + \frac{1/2}{(p-2)^2} + \frac{1/2}{p-1} \\ &= \frac{-1/2}{p-2} + \frac{1/2}{(p-2)^2} + \frac{1/2}{p-1} \\ \text{By taking } \mathcal{T}^{-1} \text{ to both sides we get :} \\ y &= -1/2 \ \mathcal{T}^{-1}\left(\frac{1}{p-2}\right) + \frac{1}{2} \ \mathcal{T}^{-1}\left[\frac{1}{(p-2)^2}\right] + \frac{1}{2} \ \mathcal{T}^{-1}\left(\frac{1}{p-1}\right) + \ \mathcal{T}^{-1}\left(\frac{\mathcal{C}}{p-1}\right) \\ \text{And,} \\ y &= -\frac{1}{2}x + \frac{1}{2}x\ln x + \frac{1}{2} + c \\ \text{Since,} \qquad y(1) = 1 \Rightarrow c_1 = \frac{3}{2} \end{aligned}$$

Conclusion: apply Al-Tememe transformations to solve linear ordinary differential equations with variable coefficients by using initial and without any initial conditions.

References :

- [1] Dennis G.Zill, " A First Course In Differential Equations with modeling application", Tenth edition, 2012.
- [2] Gabriel Nagy, "Ordinary Differential Equations" Mathematics Department, Michigan State University, East Lansing, MI, 48824. October 14, 2014.
- [3] Joel L. Schiff, "The Laplace Transform Theory and Applications", springer, 2010.
- [4] Mohammed, A.H. ,Athera Nema Kathem, "Solving Euler's Equation by Using New Transformation", Karbala university magazine for completely sciences ,volume(6), number(4), (2008),103-109.
- [5] PhD, Andr'as Domokos, "Differential Equations Theory and Applications", California State University, Sacramento, Spring, 2015.
- [6] William F. Trench, " Elementary Differential Equations " Trinity University, 2013.