

Stability for hybrid mapping of quasi-contraction in b-metric space

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Abstract:

In this paper, we prove the stability of iterative process for hybrid mappings of quasi-contraction in b-metric space. Our work generalizes and improves some results due to Czerwiket *al.* 1997, Singhet *al.* 2008 and Hashim 2011.

Mathematics Subject Classifications (2000): 54H25, 47H10.

Keywords: stable iteration,b-metric space, multivalued maps, fixed point.

1. Introduction

The first result on stability of iteration on metric spaces was given by M.Ostrowski 1956, although this type of problem was already observed M. Urabe in 1957 for real valued function. Thereafter, a number of authors have generalized and extended his result in various setting. Harder and Hicks have obtain interesting results on stability of a number of iterative procedures with examples. Rhoades (1990) and Rhoades and Saliga (2001) have a generalized various existing result and established fixed point theorems for various iterative procedures. Czerwik 1997 and Czerwik et al. 2002 has extended Ostroski's classical theorem for the stability of iterative procedure for multi-valued maps in b-metric space .in 2011 HashimA.M. studied the stability of iterative process for hybrid contraction mappings involving a single-valued and multi-valued maps in b-metric space.

Example (2.2)(Singh et al. 2008)

Let $X = \{x_1, x_2, x_3, x_4\}$ and

$$d(x_1, x_2) = b \geq 2, d(x_1, x_3) = d(x_1, x_4) = d(x_2, x_3) = d(x_2, x_4) = d(x_3, x_4) = 1$$

$$d(x_i, x_j) = d(x_j, x_i) \text{ for } i, j = 1, 2, 3, 4 \text{ and } d(x_i, x_i) = 0, i = 1, 2, 3, 4.$$

$d(x_i, x_j) \leq \frac{b}{2} [d(x_i, x_n) + d(x_n, x_j)]$ for $i, j = 1, 2, 3, 4$, and if $b > 2$, the ordinary triangle inequality does not hold. i.e. need not be a metric on X

The purpose of this paper is to study the stability of iterative process for hybrid maps satisfying quasi-contraction in b-metric space.

2. PRELIMINARIES

Definition (2.1) (Czerwik1998)

Let X be a nonempty set and let $b \geq 1$ be a given real number . A function $d : X \times X \rightarrow R^+$ (The set of positive real numbers) is called a b-metric if and only if for all $x, y, z \in X$, the following conditions are satisfied:

- (i) $d(x, y) = 0$ iff $x = y$;
- (ii) $d(x, y) = d(y, x)$;
- (iii) $d(x, z) \leq b [d(x, y) + d(y, z)]$.

The pair (X, d) is called a b-metric space.

It is clear that definition of b-metric space is an extension of usual metric space. The following example illustrates that b-metric space are more general than metric spaces.

Let (X, d) is a b-metric space.

$CL(X) = \{A : A \text{ is nonempty closed subset of } X\}$

$CB(X) = \{A : A \text{ is nonempty closed bounded subset of } X\}$

$$H(A, B) = \text{Max} \left\{ \begin{array}{ll} \sup_{x \in A} D(x, B), \sup_{y \in B} D(y, A), & \text{if the maximum exists} \\ \infty, & \text{otherwise} \end{array} \right\},$$

$$A, B \in CL(X), D(x, A) = \inf_{a \in A} d(x, a)$$

H is called a generalized Hausdorff b-metric on $CL(X)$ induced by the metric d on X .

We shall require the following Lemmas and definitions

Lemma (2.3)(Czerwik 1998)

Let (X, d) be a b-metric space, then for any $A, B, C \in CL(X)$,

- 1) $D(x, B) \leq d(x, y)$ for any $y \in B$,
- 2) $D(A, B) \leq H(A, B)$,
- 3) $H(A, C) \leq b[H(A, B) + H(B, C)]$.

Lemma(2.4) (Czerwik 1998)

Let A and B be distinct element of $CL(X)$. Let $x \in A$. Then for a given number $\lambda > 1$, there exists a point y in B such that $d(x, y) \leq \lambda H(A, B)$.

Definition (2.5) (Singh et al. 2008)

Let (X, d) be a b-metric space and $Y \subseteq X$. Let $T : Y \rightarrow CL(X), S : Y \rightarrow X, T(Y) \subseteq S(X)$. and z a coincidence

point of T and S , that is $Sz \in Tz = u$.

For any $x_0 \in Y$, let the sequence $\{Sx_n\}$ generated by the general iterative procedure.

$$Sx_{n+1} \in f(T, x_n) \quad n = 1, 2, \dots$$

converge to an element $u \in X$. Let

$\{Sy_n\} \subseteq X$ be an arbitrary sequence and let

$$\varepsilon_n = H(y_{n+1}, f(T, y_n)), \quad n = 0, 1, 2, \dots$$

Then the iterative procedure $f(T, x_n)$ is (S, T) -stable, or stable with respect

to (S, T) if and only if $\lim_{n \rightarrow \infty} \varepsilon_n = 0$
 implies that $\lim_{n \rightarrow \infty} S y_n = u$.

This definition in metric spaces with $b = 1$ and (The identity map) is due to Harder and Hick (1988a, 1988b) and Rhoades (1990, 1993) and Rhoades and Saliga (2001) and Singh and Chadha (1995).

Definition (2.6) (Rao and Swamy in 2013)

Let (X, d) be a b-metric space. Let $T : X \rightarrow CB(X)$ be multivalued and $S : X \rightarrow X$ be a self-map. The hybrid pairs (T, S) are said to be q-multivalued quasi-contraction if there exists $0 \leq q < 1$ such that

$$H(Tx, Ty) \leq qM(x, y) \quad (2.1)$$

for all $x, y \in X$, where,

$$M(x, y) = \max \{d(Sx, Sy), d(Sx, Tx), d(Sy, Ty), d(Sx, Ty), d(Sy, Tx)\}$$

Theorem (2.7) (Rao and Swamy in 2013)

Let (X, d) be a b-metric space. Suppose that $S : X \rightarrow X$ and $T : X \rightarrow CB(X)$.

Suppose that the hybrid pair (T, S) is q-multivalued quasi-contraction,

$TX \subseteq SX$ and SX is complete.

Assume that $q < \frac{1}{b^2 + b}$. Then

- i) T and S have coincidence points in X (or)
- ii) The pairs (T, S) have a common coincidence point.

Lemma (2.8) see also (Rhoades 1993, Czerwik et al. 2002)

Let $\{\varepsilon_n\}$ be a sequence of non negative real numbers. Let $s_n = \sum_{i=0}^n k^{n-i} \varepsilon_i$

where $0 \leq k < 1$. Then

$$\lim_{n \rightarrow \infty} \varepsilon_n = 0 \text{ iff } \lim_{n \rightarrow \infty} s_n = 0.$$

In this paper, we prove the stability of quasi-contraction for hybrid mappings

3.Main Results

Theorem (3.1)

Let (X, d) be a b-metric space.

Suppose that SX or TX is a complete subspace of X and let

$$S : X \rightarrow X \text{ and } T : X \rightarrow CL(X)$$

and suppose that the hybrid pairs (S, T) is q-multivalued quasi-contraction. Let z be a coincidence point of T and S i.e $z = Su \in Tu$.

For any $x_0 \in X$ let the sequence $\{Sx_n\}$ generated by $Sx_{n+1} \in Tx_n$

converge to $z \in X$. Let $\{Sy_n\} \subseteq X$ be an arbitrary sequence and define

$$\varepsilon_n = H(Sy_{n+1}, Ty_n), \quad n = 0, 1, 2, \dots, \quad k = bq < 1 \text{ and } q < \frac{1}{b^2 + b}, \text{ then}$$

$$1) \quad d(z, Sy_{n+1}) \leq bd(z, Sx_{n+1}) + b(b\alpha)^{n+1}d(x_0, y_0) + b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r}d(Sx_r, Tx_r) +$$

$$b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

$$2) \quad \text{If } Tz \text{ is singleton then } \lim_{n \rightarrow \infty} y_n = z \text{ if and only if } \lim_{n \rightarrow \infty} \varepsilon_n = 0.$$

Proof:

From (3.1) for any $x, y \in X$, one of the following holds:

$$H(Tx, Ty) \leq qd(Sx, Sy),$$

$$H(Tx, Ty) \leq qD(Sx, Tx) \\ \leq qH(Sx, Tx);$$

$$H(Tx, Ty) \leq qD(Sy, Ty) \\ \leq qb[H(Sy, Sx) + H(Sx, Ty)]$$

$$\leq qb[d(Sy, Sx)] + qb[bH(Sx, Tx) + bH(Tx, Ty)]$$

$$\leq qb[d(Sy, Sx)] + qb^2H(Sx, Tx) + qb^2H(Tx, Ty)$$

$$\text{i.e. } H(Tx, Ty) \leq \frac{qb}{1 - qb^2}d(Sy, Sx) + \frac{qb^2}{1 - qb^2}H(Sx, Tx)$$

$$\leq \frac{k}{1 - kb}d(Sy, Sx) + \frac{kb}{1 - kb}H(Sx, Tx)$$

$$H(Tx, Ty) \leq qd(Sx, Ty) \\ \leq qb[d(Sx, Tx) + H(Tx, Ty)]$$

$$\leq \frac{qbH(Sx, Tx)}{(1 - qb)}$$

$$\leq \frac{k}{1 - k} H(Sx, Tx)$$

$$H(Tx, Ty) \leq qd(Sy, Tx)$$

$$\leq qb[d(Sy, Sx) + H(Sx, Tx)]$$

Therefore, in all cases we get,

$$H(Tx, Ty) \leq \alpha d(Sx, Sy) + b\alpha H(Sx, Ty), \text{ where } \alpha = \frac{b^2 q}{1 - b^2 q}, b\alpha < 1$$

$$d(Sx_{n+1}, Sy_{n+1}) \leq H(Tx_n, Sy_{n+1})$$

$$\leq b[H(Tx_n, Ty_n) + H(Ty_n, Sy_{n+1})]$$

$$\leq b[\alpha d(Sx_n, Sy_n) + b\alpha H(Sx_n, Ty_n) + \varepsilon_n]$$

$$\leq b\alpha d(Sx_n, Sy_n) + b^2\alpha H(Sx_n, Ty_n) + b\varepsilon_n$$

$$\leq b^2\alpha[H(Tx_{n-1}, Ty_{n-1}) + H(Ty_{n-1}, Sy_n)] + b^2\alpha H(Sx_n, Ty_n) + b\varepsilon_n$$

$$\leq b^2\alpha[\alpha d(Sx_{n-1}, Sy_{n-1}) + b\alpha H(Sx_{n-1}, Ty_{n-1}) + H(Ty_{n-1}, Sy_n)] +$$

$$b^2\alpha H(Sx_n, Ty_n) + b\varepsilon_n$$

$$\leq b^2\alpha^2 d(Sx_{n-1}, Sy_{n-1}) + (b^2\alpha^2)bH(Sx_{n-1}, Ty_{n-1}) + b^2\alpha \varepsilon_{n-1} +$$

$$b^2\alpha H(Sx_n, Ty_n) + b\varepsilon_n$$

$$\leq (b\alpha)^2[d(Sx_{n-1}, Sy_{n-1}) + (b\alpha)^2 b d(Sx_{n-1}, Ty_{n-1}) + b^2\alpha H(Sx_n, Ty_n)] +$$

$$b(\alpha b\varepsilon_{n-1} + b\varepsilon_n)$$

where $k = bq < 1$

Repeating this process (n-1)-times we get (1)

$$d(Sx_{n+1}, Sy_{n+1}) \leq (b\alpha)^{n+1} d(Sx_0, Sy_0) + b^2\alpha \sum_{r=0}^n (b\alpha)^{n-r} d(Sx_r, Ty_{r+1}) +$$

$$b \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

$$d(z, Sy_{n+1}) \leq bd(z, Sx_{n+1}) + bd(Sx_{n+1}, Sy_{n+1})$$

$$\leq bd(z, Sx_{n+1}) + b(b\alpha)^{n+1} d(x_0, y_0) + b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r} d(Sx_r, Tx_r) + b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

Assume $\lim_{n \rightarrow \infty} Sy_n = z$.

$$\varepsilon_n = H(Sy_{n+1}, Ty_n) \leq bd(Sy_{n+1}, Sx_{n+1}) + bH(Tx_n, Ty_n)$$

$$\leq bd(Sy_{n+1}, Sx_{n+1}) + [\alpha d(Sx_n, Sy_n) + b\alpha H(Sx_n, Tx_n)]$$

Letting $n \rightarrow \infty$, we obtain $\varepsilon \rightarrow 0$

Suppose that $\lim_{n \rightarrow \infty} \varepsilon_n = 0$. since $0 \leq b\alpha < 1$ and $\alpha b < 1$

And $\lim_{n \rightarrow \infty} Sx_n = z$, from (1) we obtain (2) by applying lemma (3.2.5)

$$\lim_{n \rightarrow \infty} d(z, Sy_{n+1}) \leq \lim_{n \rightarrow \infty} [b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r} d(Sx_r, Tx_r) + b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r]$$

Let A denote the lower triangular matrix with entries $a_{nr} = (b\alpha)^{n-r}$, then $\lim_{n \rightarrow \infty} a_{nr} = 0$

for each r and $\lim_{n \rightarrow \infty} \sum_{r=0}^n a_{nr} = \lim_{n \rightarrow \infty} \left(\frac{1 - (b\alpha)^{n+1}}{1 - b\alpha} \right) = \frac{1}{1 - b\alpha}$. Therefore,

A is multiplicative i.e for any converge sequence

$$\{b_n\}, \lim_{n \rightarrow \infty} A(b_n) = \frac{1}{1 - b\alpha} \lim_{n \rightarrow \infty} b_n. \text{ (of, P.692) B. E. Rhoades 1993. Thus,}$$

$$\lim_{n \rightarrow \infty} b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r} d(Sx_r, Tx_r) = 0.$$

In theorem (3.3.1) when we put $S = Id$ (Identity map)

Corollary (3.2):

Let (X, d) be a b-metric space. Suppose that TX is a complete subspace of X and let $T : X \rightarrow CL(X)$ and suppose that T is q-multivalued quasi-contraction. Let z be a fixed point of T i.e. $z \in Tz$. For any $x_0 \in X$ let the sequence $\{x_n\}$ generated by $x_{n+1} \in Tx_n$ converge to z . Let $\{y_n\} \subseteq X$ be an arbitrary sequence and define $\varepsilon_n = H(y_{n+1}, Ty_n), n = 0, 1, 2, \dots, k = bq < 1$ and $q < \frac{1}{b^2 + b}$. Then

1)

$$d(z, y_{n+1}) \leq bd(z, x_{n+1}) + b(b\alpha)^{n+1}d(x_0, y_0) + b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r}d(x_r, Tx_r) + b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

2) Further, If Tz is singleton then $\lim_{n \rightarrow \infty} y_n = z$ if and only if $\lim_{n \rightarrow \infty} \varepsilon_n = 0$.

When S and T are a single-valued maps we obtain the corollary (3.3.3).

Corollary (3.3):

Let (X, d) be b-metric space. Suppose that SX or TX is a complete subspace of X and let $S : X \rightarrow X$ and $T : X \rightarrow X$ and suppose that the hybrid pairs (T, S) is q-singlevalued quasi-contraction let z be a coincidence point of T and S i.e.

$z = Su = Tu$ for any $x_0 \in X$ let the sequence $\{Sx_n\}$ generated by $Sx_{n+1} = Tx_n$ converge to z , let $\{Sy_n\} \subseteq X$ be an arbitrary sequence and define $\varepsilon_n = d(Sy_{n+1}, Ty_n), n = 0, 1, 2, \dots, .K = bq < 1$ and $q < \frac{1}{b^2 + b}$. Then:

1) $d(z, Sy_{n+1}) \leq bd(z, Sx_{n+1}) + b(b\alpha)^{n+1}d(x_0, y_0) + b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r}d(Sx_r, Tx_r) +$

- 2) If Tz is singleton then $\lim_{n \rightarrow \infty} y_n = z$ if and only if $\lim_{n \rightarrow \infty} \varepsilon_n = 0$.

If $S = I$ (the identity map) we obtain the corollary (3.4) as follows

Corollary (3.4):

Let (X, d) be b-metric space. Suppose that TX is a complete subspace of X and let $T: X \rightarrow X$ and suppose T is q -singlevalued quasi-contraction let z be a fixed point of T i.e. $z = Tz$ for any $x_0 \in X$ let the

sequence $\{x_n\}$ generated by $x_{n+1} = Tx_n$ converge to z , let $\{y_n\} \subseteq X$ be an arbitrary sequence and define $\varepsilon_n = d(y_{n+1}, Ty_n), n = 0, 1, 2, \dots, K = bq < 1$ and $q < \frac{1}{b^2 + b}$. Then

1)

$$d(z, y_{n+1}) \leq bd(z, x_{n+1}) + b(b\alpha)^{n+1}d(x_0, y_0) + b^3\alpha \sum_{r=0}^n (b\alpha)^{n-r}d(x_r, Tx_r) + b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

$$b^2 \sum_{r=0}^n (b\alpha)^{n-r} \varepsilon_r$$

- 2) If Tz is singleton then $\lim_{n \rightarrow \infty} y_n = z$ if and only if $\lim_{n \rightarrow \infty} \varepsilon_n = 0$.

Remark (3.5)

1) Theorem (3.1) generalized and extension of theorem (3.2) Hashim (2011), and theorem of S.L singh et.al. (1995). It is also a generalization and extension of theorem (4.3) of Singh et.al(2008). Indeed theorem (3.3.1) is a generalization and extension of a multivalued of results in the literature pertaining to single-valued and multivalued cases .

2) Corollary (3.4) with $b = 1$ generalized Ostrowski's stability theorem (1967) single-valued map.

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الخلاصة

تضمن هذا البحث برهان استقراريه الدوال الهجينة من النوع **Quasi-Contraction** في الفضاء المترى ب وكذلك تم تعميم وتطوير نتائج العديد من الباحثين أمثال

Czerwiket.al.1997, Singhet.al. 2005,Singh et.al. 2008 and Hashim 2011.